

DRAFT: Open-source Fuel Cell Simulation Toolbox (OpenFCST)

- User and Developer's Reference Guide

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Contents

1	Introduction	7
1.1	Overview of the program	7
1.2	About FCST	8
1.3	License	9
1.4	Release changes	9
I	User's Guide	11
2	Installation	13
2.1	Downloading FCST	13
2.1.1	Users	13
2.1.2	Developers	13
2.2	Installing OpenFCST	13
2.2.1	System requirements	13
2.2.2	Installation steps	14
3	Pre-processor	15
3.1	FuelCellShop::Geometry Namespace	15
3.2	Developing a mesh in Salome	15
3.2.1	Tutorial	15
3.2.2	Meshing with Hexotic	23
3.3	Salome meshing using python scripts	26
3.3.1	Introduction	26
3.3.2	Scripting Examples	27
4	Running FCST	29
4.1	Fuel Cell Analysis Using FCST	29
4.2	Fuel Cell Parametric Study using FCST	31
4.2.1	Main Application File	31
4.2.2	Data Application File	32
4.2.3	Parameter/Optimization Application File	43
4.3	Optimization using FCST	46
4.4	Multi-Objective Optimization using FCST	51
4.5	DAKOTA Methods	52
4.6	Fuel Cell Design & Optimization Using FCST	53
4.6.1	FCST classes that interact with DAKOTA (Developers Only)	53
5	Post-processor	57

II Developer's Reference Guide (Under development)	59
6 Preliminaries	61
6.1 Setting up FCST under KDevelop	61
6.1.1 Formatting OpenFCST files	61
7 FCST structure	63
7.1 Directory tree	63
7.2 Understanding FCST Architecture	64
7.3 Understanding FCST Applications: The FCST tutorials	64
7.4 FCST Applications	64
7.4.1 Data files	64
7.5 Namespace structure	64
7.6 Layers Namespace	67
7.7 Materials Namespace	67
7.8 Contributing libraries	67
7.8.1 APPFRAME	68
7.8.2 COLDAE Interface	69
7.8.3 Adding a new version of a contribution library to the repository	71
8 Coding Guidelines (DRAFT)	73
8.1 Class and Member Naming Conventions	73
8.2 Class and Member Document Strings	74
8.3 Assertions and exception handling	75
9 Developing Documentation in FCST	77
9.1 Developing the User and Developer's Reference Guide	77
9.2 Developing DOxygen documentation	77
9.2.1 TODO list in HTML documentation	77
9.2.2 Linking to other functions	77
10 Development Process	79
10.1 Proposed Development Cycle	79
10.2 Test Driven Development	79
10.2.1 Unit Tests	81
10.2.2 TDD Implementation in the FCST	81
10.2.3 Implementing a new test suite	84
10.2.4 Refactoring	84
10.2.5 Unit Standards	86
11 Tracking and Ticketing System for FCST	87
11.1 Tracking and Ticketing System Overview	87
11.2 Using the Ticketing System	87
12 Daily FCST testing suite: CTest and CDash	89
12.1 Testing your code in your local directory	89
13 Useful Programming Tips	91
13.1 Memory Leak Detection	91
13.2 Working with pointers	91
13.3 Including files to the include files	91
13.4 Subversion tips	91
13.4.1 Setting the \$Id\$ Tag in Subversion	91

13.5	Troubleshooting	92
13.5.1	Including new virtual functions in already existing classes	92
13.5.2	Corrupted double-linked list error	93
13.6	Appendix	96
13.6.1	Example test script	96

Chapter 1

Introduction

1.1 Overview of the program

The Fuel Cell Simulation Toolbox (FCST) is an open-source mathematical modelling package for polymer electrolyte fuel cells. FCST builds on top of the open-source finite element libraries [deal.II](#), therefore many of its requirements in terms of operating systems and such are the same as for [deal.II](#). FCST is distributed under the MIT License. FCST has been developed as a modular toolbox from which you can develop your own applications. It contains a database of physical phenomena equations, fuel cell layers and materials, and kinetics mathematical models. In addition, it already contains several applications that allow you to simulate different fuel cell components. For example, you can simulate a cathode electrode (using either a macrohomogeneous or an ionomer-filled agglomerate model), an anode electrode or a complete membrane electrode assembly. The applications already provided in FCST have been validated with respect to experimental data in the literature [\[5\]](#) as well as numerical results from another model implemented in a commercial package. A thorough description of the model and the validation is presented in [\[2\]](#).

FCST is being developed at the [Energy Systems Design Laboratory](#) at the University of Alberta in collaboration with the [Automotive Fuel Cell Cooperation Corp.](#) that, together with the [Natural Science and Engineering Research Council of Canada](#) has provided the majority of the funding required to develop this code. The goal of FCST is that research groups in academia and in industry use the current toolbox to better understand fuel cells and to develop new physics and material databases that can then be integrated in the current library.

FCST is an integrated open-source tool for fuel cell analysis and design. It seamlessly integrates several open-source pre-processing, finite element and post-processing tools in order to analyze fuel cell systems. FCST contains a build-in mesh generator as well as it can import quadrilateral meshes generated with the open-source pre-processor Salome [Salome](#) if your problem requires to simulate more complex geometries. The physics and material database in FCST allow you to setup the governing equations for the most important physical processes that take place in a fuel cell. FCST already implements the weak form for many governing equations that are finally solved using the finite element open-source libraries [deal.II](#). In order to analyze your results, FCST can output your results to .vtk files that can easily be read with the open-source post-processor [Paraview](#). FCST is not only an analysis tool. FCST also is also integrated with the design and optimization package [Dakota](#). Therefore, it can be used for design and optimization as well as parameter estimation, e.g. reference [\[2, 3, 4, 5\]](#).

FCST is still under development. If you like the library and would like it to continue to be developed please help the developers in the following ways:

- If you are an industrial researcher that is considering using FCST for research and development in the company, please consider contacting the developers in order to develop a research program with them.
- If you are either an industrial or academic researcher using the library, please make sure to cite the FCST libraries in your publications. Please cite any relevant publication by the FCST developers as

well as the current reference [1].

- If you are either an industrial or academic researcher using the library and you have developed a new physics model or material database entry, please consider submitting the class to the developers so that it can be integrated with the newest version of FCST.
- If you are an industrial researcher that is considering using FCST for research and development in the company, please consider hiring the graduate students that develop FCST, i.e. the graduate students from the [Energy Systems Design Laboratory](#) at the University of Alberta.

FCST is still under development. Currently, the developers are working on:

- Improving the code readability New classes are being develop to try to make the code more easy to understand and more modular.
- Developing a convective gas and liquid transport model for the electrodes
- Developing a Navier-Stokes solver for gas transport in the fuel cell channels
- Developing a multi-scale framework for electrode analysis
- Developing a non-isothermal membrane electrode model

1.2 About FCST

FCST was originally conceived by M. Secanell in 2006 while doing his Ph.D. at the University of Victoria [2]. In 2004, M. Secanell developed a small set of routines that were used to setup the governing equations for a fuel cell cathode in two-dimensions. The governing equations were first linearized and then the weak form of the equations was implemented and solved using the [deal.II](#) finite element libraries [3]. In 2006, after attending a [deal.II](#) workshop in Heidelberg, Germany, and discussing the idea of creating an open-source code for fuel cells based on [deal.II](#) with Dr. Guido Kanschat and Dr. Wolfgang Bangerth, M. Secanell decided to integrate the routines he had developed into AppFrame, an application framework developed by Dr. Guido Kanschat, thereby originating the idea of a toolbox that could be used to create modules or applications for fuel cell analysis. From 2006 to 2008, FCST development continued with the implementation of a complete membrane electrode assembly model; however, with M. Secanell as a unique developed the code was too rough and disorganized to result in an open-source fuel cell package that the research community could use. In 2009, once M. Secanell joined the University of Alberta, the idea of developing FCST was solidified. Thanks to the funding provided by the [Automotive Fuel Cell Cooperation Corp.](#), [MITACS](#) and the [Natural Science and Engineering Research Council of Canada](#), a group of core developers was established at the [Energy Systems Design Laboratory](#) at the University of Alberta. The current core of developers re-developed the majority of the classes in order to increase the modularity, usability and reliability of the code. Currently, FCST is used by 6-8 researchers at two different laboratories, it is tested nightly for errors and it contains a bug tracking site to report any issues with its performance.

The current group of FCST developers is formed by:

- M. Secanell, Associate Professor, Energy Systems Design Laboratory, University of Alberta, Canada
Responsible for overall framework (base class concepts), optimization interface, electronic, protonic, membrane water transport, Fick's gas transport and kinetics
- A. Putz, Senior Research Scientist, Automotive Fuel Cell Cooperation Corp.
Responsible for plug-points and AFCC contributions
- V. Zingan, Post-doctoral Fellow, Energy Systems Design Laboratory, University of Alberta, Canada
Responsible for overall framework (base class concepts), Navier-Stokes, Darcy and multi-component fluid flow physical models and applications

- M. Moore, M.Sc. graduate from the Energy Systems Design Laboratory, University of Alberta, Canada
Responsible for `fcst_install` script, double-trap kinetics model for ORR reaction and multi-scale framework (1D agglomerate models)
- M. Bhaiya, M.Sc. Student, Energy Systems Design Laboratory, University of Alberta, Canada
Responsible for overall framework (base class concepts) and thermal physical models and applications
- P. Wardlaw, M.Sc. Student, Energy Systems Design Laboratory, University of Alberta, Canada
Responsible for `fcst_install` script and multi-scale framework (1D agglomerate models)
- K. Domican, M.Sc. Student, Energy Systems Design Laboratory, University of Alberta, Canada
Responsible for optimization interface and documentation

Other scientists that have also contributed substantial portions of code to FCST are:

- G. Kanschat, Universitt Heidelberg
Developer of AppFrame (now part of deal.ii as MeshWorker)
- P. Dobson, M.Sc. graduate from the Energy Systems Design Laboratory
Developed parts of overall framework (base class concepts), optimization interface and multi-scale framework (1D agglomerate models)
- Ali Malekpourkoupaei, former M.Sc. graduate student at the Energy Systems Design Laboratory
Developed classes PureGas and classes to compute binary diffusivity (together with M. Secanell)

1.3 License

The Fuel Cell Simulation Toolbox (FCST) is distributed under the MIT License.

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1.4 Release changes

- May 18, 2010: Added variable scaling to method section for OPT+ and NL2SOL. In order to do so I modified *optimization_blockmatrix_application.cc* > *declare_parameters* and *dakota_application.cc* and *.h* to include a new bool variable and to read it.
- May 19, 2010:

- The reference exchange current density is now read in $\mu\text{A}/\text{cm}^2$ in order to help optimization/least squares since Dakota only allows scaling up to $1\text{e-}3$
 - Changes to volume fraction and *catalyst_layer*
 - Is *epsilon_agg* modified inside the electrochemical equations?
- July 10, 2010:I moved "Optimization options section" to *dakotadirectinterface* (where it belongs). Now, if you want to run a single run, you have to comment all the information about optimization

Part I

User's Guide

Chapter 2

Installation

2.1 Downloading FCST

2.1.1 Users

OpenFCST can be found at the [OpenFCST](#) website. In the download section you will be able to find a .tar file with the latest release. Download the .tar file and download it at an appropriate location.

2.1.2 Developers

The latest version of OpenFCST is hosted in a repository at the University of Alberta. To download the latest version of FCST type the following on your terminal (you will require a username and password to download the code):

```
1 $svn checkout http://129.128.14.197/esdl/fcst/
```

If you do not have a username and password contact M. Secanell (secanell@ualberta.ca).

If you already have already checkout a version of the code, you can update your local copy by typing the following on your terminal

```
1 $svn update
```

2.2 Installing OpenFCST

2.2.1 System requirements

FCST is developed on Linux and compiled using the GCC compiler. The configure script that FCST uses relies heavily on the configure script from are the same as those used by [deal.II](#). As [deal.II](#), even though the FCST developers work on a Linux operating system, the FCST should not be platform specific and we strive to keep the source code C++ Standard compliant.

FCST developers perform nightly compilation tests on the following OS

- OpenSUSE 12.X
- Fedora 18

These are the operating systems that the FCST developers recommend.

If you would like to try to run the code under a Windows environment, you can try using either the Cywin or MinGW environments.

The following software needs to also be installed in your computer in order for FCST to compile:

- GNU make, version 3.78 or later (or any other generator supported by CMake)
- GCC
- BLAS and LAPACK libraries
- MPICH compiler
- For generating the documentation: DOxygen

In addition the following packages might be useful if you are planning on developing new classes for FCST:

- For debugging programs, we have found that the GNU debugger GDB is an invaluable tool. GDB is a text-based tool not always easy to use; kdbg, is one of many graphical user interfaces for it.
- Most integrated development environments like kdevelop or Eclipse have built in debuggers as well.

2.2.2 Installation steps

Fuel Cell Simulation Toolbox is a fuel cell simulation package developed using several OpenSource libraries such as the deal.II libraries, the deal.II Application Framework and Shop, DAKOTA and COLDAE. In order to run without any difficulties, Fuel Cell needs to compile and link to all these applications which are provided with the code under the folder `/contrib` (Please note that each package is distributed under a different license).

FCST contains a script to compile all packages simultaneously. To compile FCST and all other libraries use the following:

```
1 $ ./fcst_install --without-Dakota --with-MPI --cores=4
```

Since Dakota is not included in the openFCST release, we have selected to compile FCST without without Dakota. We use the default MPI, so we specify the MPI flag without a path. Finally, we select to compile on four cores to speed up the compilation process.

The install script assumes the default path for the MPICH compiler and that all the libraries are in `./contrib`. If you already have a version of deal.II and you would like to use that version, use the flags `--with-deal`. For more information on the script options type

```
1 $ ./fcst_install --help
```

Chapter 3

Pre-processor

In order to generate a fuel cell domain using FCST two options are available:

- Use the classes under `FuelCell::Geometry` namespace
- Read in a mesh generated using an open source mesh generator such as Salome

3.1 FuelCellShop::Geometry Namespace

Namespace `FuelCellShop::Geometry` contains classes to generate a cathode and anode fuel cell electrode, an spherical agglomerate; and, a membrane electrode assembly with five or seven layers (i.e., with and without micro porous layer). To use these classes, you simply need to create an object of the class. Then, use the `declare_parameters` member function to define the variables required in the input file, initialize the object calling `initialize` and generate the grid using `generate_grid`. For example,

```
1 //Create object
2 FuelCellShop::Geometry::PemfcMPL<dim> grid;
3 //Declare the necessary variables in the ParameterHandler deal.II object
4 grid.declare_parameters(param);
5 //Once the ParameterHandler object has been initialized by reading from file,
6 //initialize the geometry variables
7 grid.initialize(param);
8 //Generate the mesh and store it in the deal.II::Triangulation variable tr
9 grid.generate_grid(*this->tr);
```

3.2 Developing a mesh in Salome

SALOME is an open-source software that provides a generic platform for pre-Processing. SALOME is a cross-platform solution that is distributed as open-source software under the terms of the GNU LGPL license. You might download both the source code and executable files from the [Salome site](#).

3.2.1 Tutorial

This short tutorial demonstrates how to create a simple mesh in Salome, define material and boundary indicators, and adapt all of this to the needs of the deal.II library.

The object we would like to mesh is represented by a two dimensional H-shaped domain as shown on Figure 3.1.

deal.II only works with meshes composed of either quadrilaterals in 2D or hexahedral in 3D. The current version of Salome is only able to produce these type of meshes with geometries that have outer boundary composed exactly of 4 pieces in 2D, e.g. see Figure 3.2, and 6 pieces in 3D, e.g. see Figure 3.3. In order to

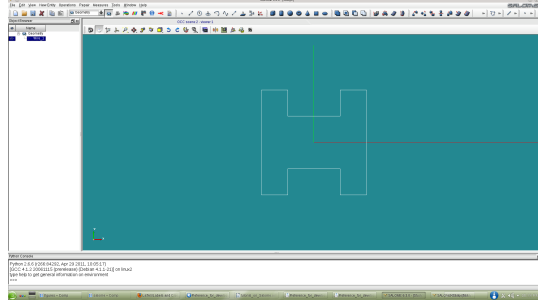


Figure 3.1: H-shaped domain.

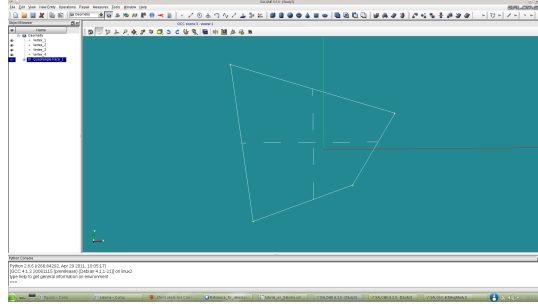


Figure 3.2: Linear quadrilateral.

increase the quadrilateral and hexahedral properties of Salome however, a commercial package is available called Hexotic distributed by Distine (For more information, please visit the following [site](#))

The two dimensional H-shaped domain shown on Figure 3.1 has 12 pieces of the outer boundary and hence can not be meshed in Salome directly by means of quadrilaterals. If Hexotic is not available, then we can mesh the domain by splitting it into 3 parts such that each of these parts would have 4 fragments of the outer boundary. Then we mesh each of these parts and combine them into the H-shaped domain.

Let us do that step by step:

- Run Salome, **File** → **New**, and click on the **Geometry** button on the upper toolbox. We are now in the Geometry module of Salome, and the first thing we need to do is to define 12 main 2D points of the object: 1(-1, -1), 2(-0.5, -1), 3(-0.5, 1), 4(-1, 1), 5(-0.5, -0.5), 6(0.5, -0.5), 7(0.5, 0.5), 8(-0.5,

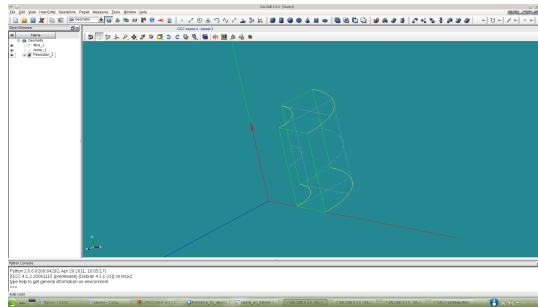


Figure 3.3: Quarter of cylindrical shell.

0.5), 9(0.5, -1), 10(1, -1), 11(1, 1), 12(0.5, 1). To create any of these points, we go to **New Entity** → **Basic** → **Point**, specify the respective fields **X:**, **Y:**, and **Z:**, and push **Apply** and **Close** button. Note that instead of **New Entity** → **Basic** → **Point** we can simpler choose **Create a point** on the upper toolbox.

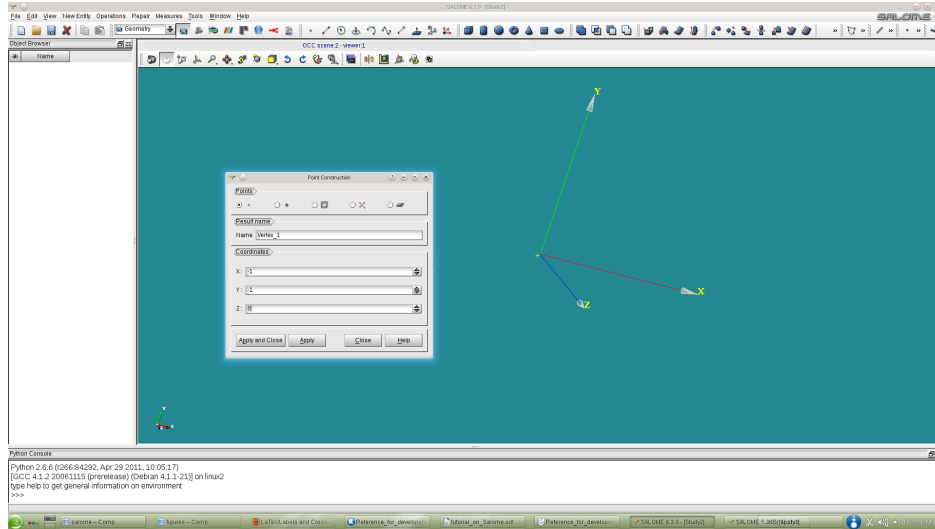


Figure 3.4: How to create a point.

After initializing all the points declared above, we have the following picture:

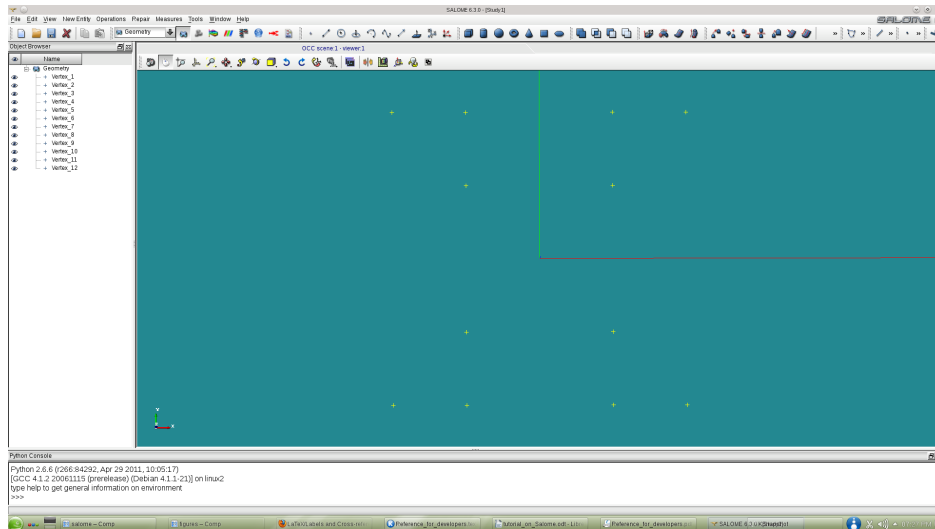


Figure 3.5: All points.

- At the next step we create 3 quadrangle faces. Each of these faces consists of 4 point: 1(1, 2, 3, 4), 2(5, 6, 7, 8), 3(9, 10, 11, 12). To create a quadrangle face, we go to **New Entity** → **Blocks** → **Quadrangle Face**, fill out the fields **Vertex 1**, **Vertex 2**, **Vertex 3**, and **Vertex 4** with the points from above, and push **Apply** and **Close** button:

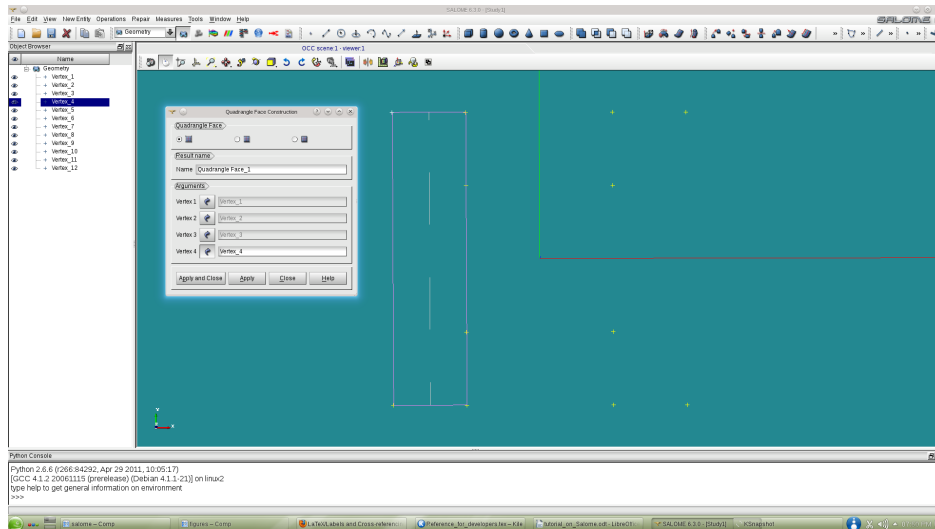


Figure 3.6: How to create a quadrangle face.

It is what we have when all the quadrangle faces have been created:

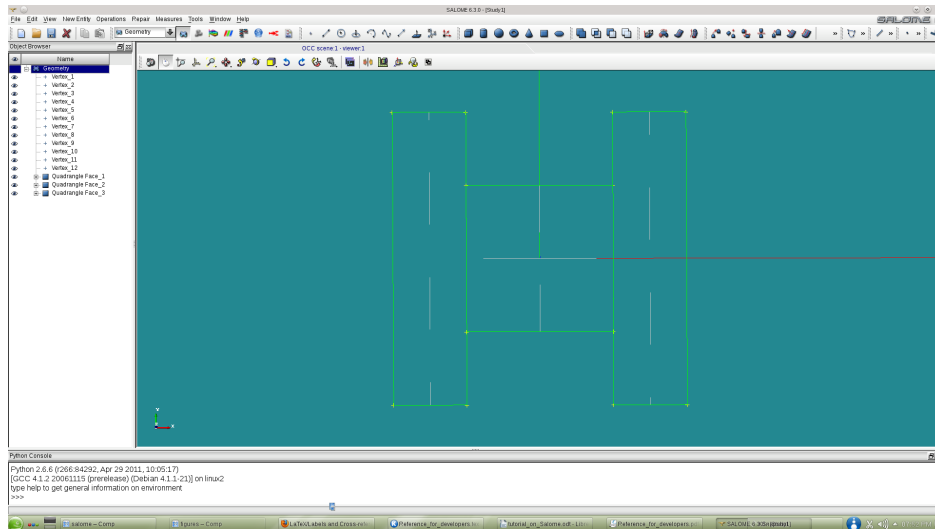


Figure 3.7: All quadrangle faces.

- At this point we have done with the Geometry module of Salome, and switch our attention to the Mesh module just by clicking the **Mesh** button on the upper toolbox. To create an appropriate mesh on each of the quadrangle faces, we go to **Mesh** → **Create Mesh**, where we pass the respective quadrangle face to the **Geometry** field. Once that is done, we choose **Quadrangle (Mapping)** from drop-down menu of the **Algorithm** field:

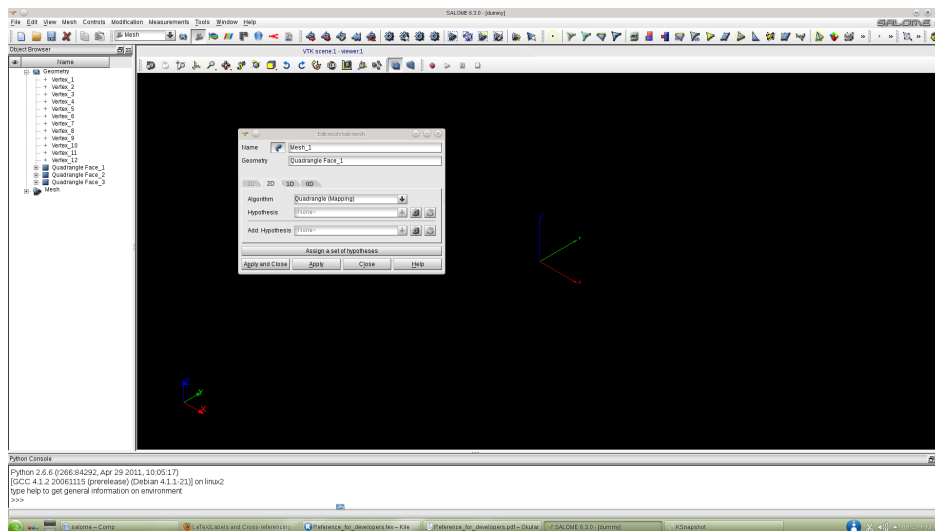


Figure 3.8

After that we click **1D** tab and check that **Algorithm** is set up to **Wire discretization**. The number of 1D hypotheses is available here. We choose the one which called **Local Length** and set up the parameters of this hypothesis as follows:

After clicking **OK** the name of **Hypothesis** field should change to **Local Length_1**. Then **Apply and Close**, mouse right click on the **Mesh_1** and **Compute**:

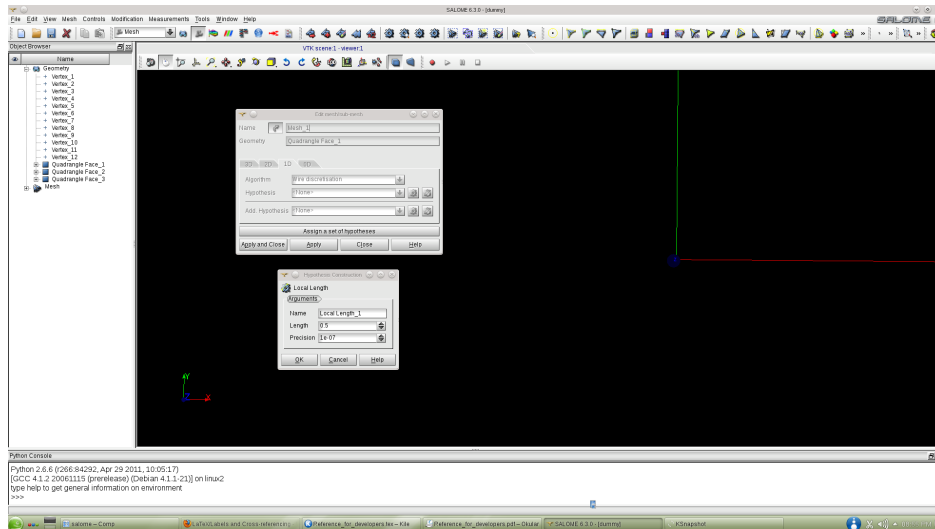


Figure 3.9

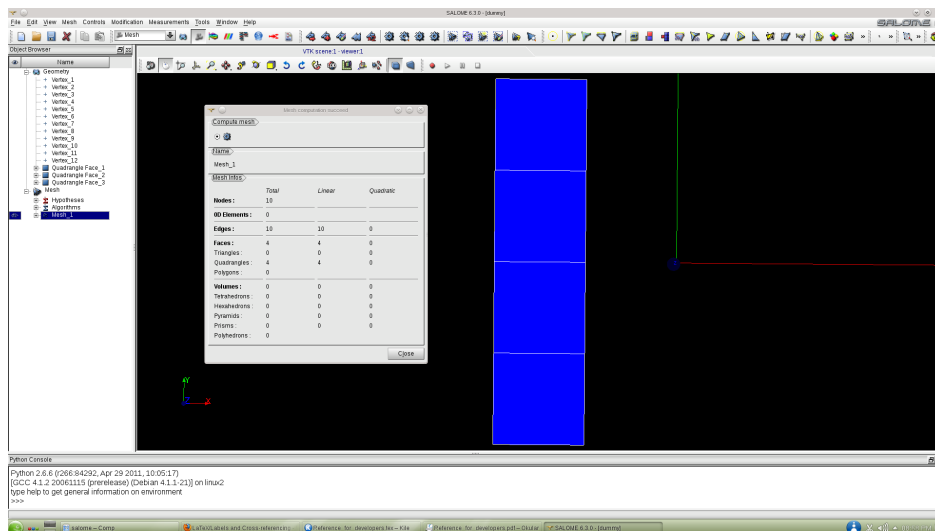


Figure 3.10

After applying this strategy to all the quadrangle faces we have something like this:

- Let us now assign material ids to all the cells we have created. For instance, all the cells of Mesh_1 have material id = 1, those belong to Mesh.2 - material id = 2, and the cells from Mesh.3 are supposed to have material id = 3. For instance, mouse right click on the **Mesh_1**, then choose **Create Group**. On this dialog box we set the following parameters:

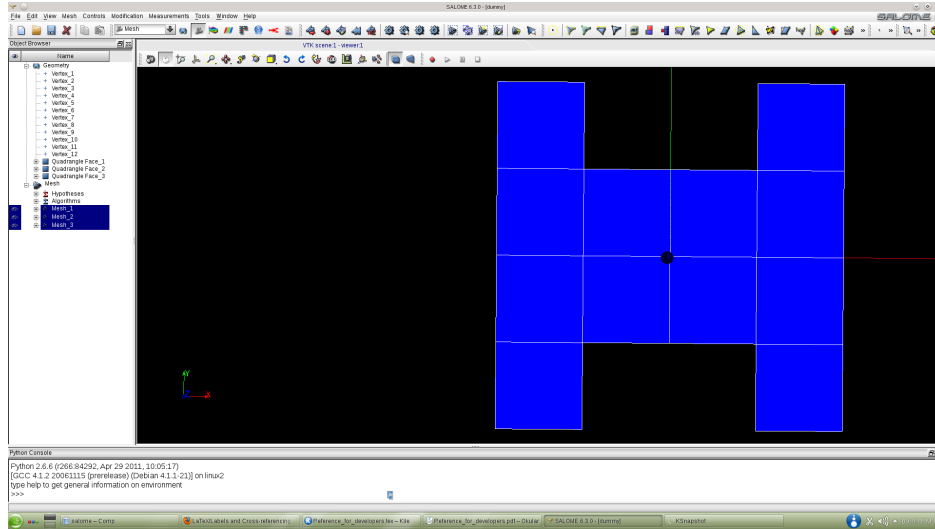


Figure 3.11

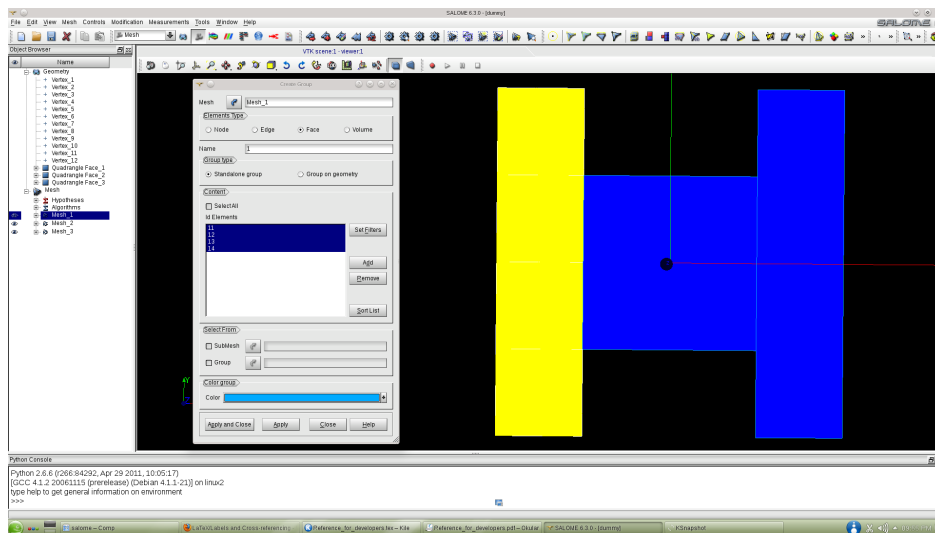


Figure 3.12

Hint: To add the cells to the **Id Elements** field, push and hold the Shift button on your keyboard and choose the cells by clicking the mouse left button. After all the desired cells have been highlighted, click **add** in the Create Group dialog window.

- Absolutely the same technique is used when we define the boundary ids. The only thing we should remember that the internal edges of the future compound mesh are not allowed to have the boundary ids. This restriction comes from deal.II limitations. As an example see the picture below:
- Finally, we create a compound mesh by simply merging all previously created meshes: **Mesh** → **Build Compound**:

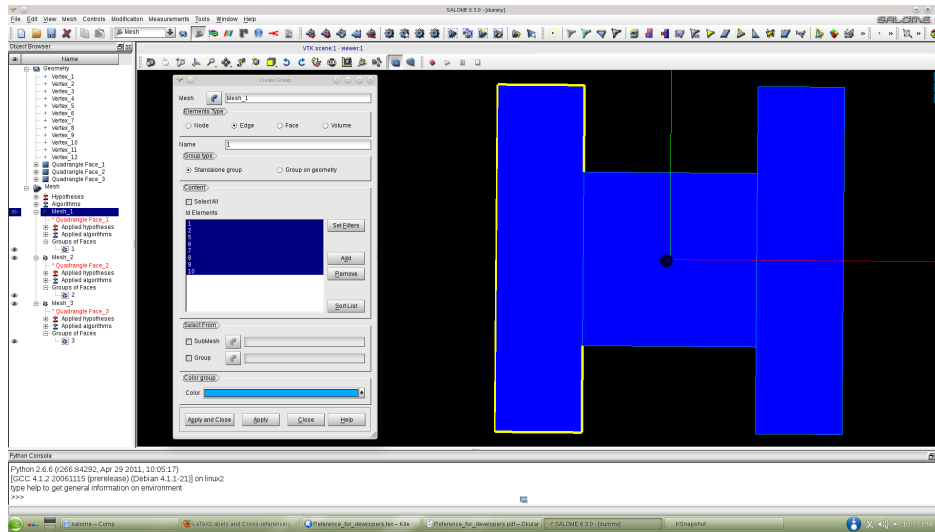


Figure 3.13

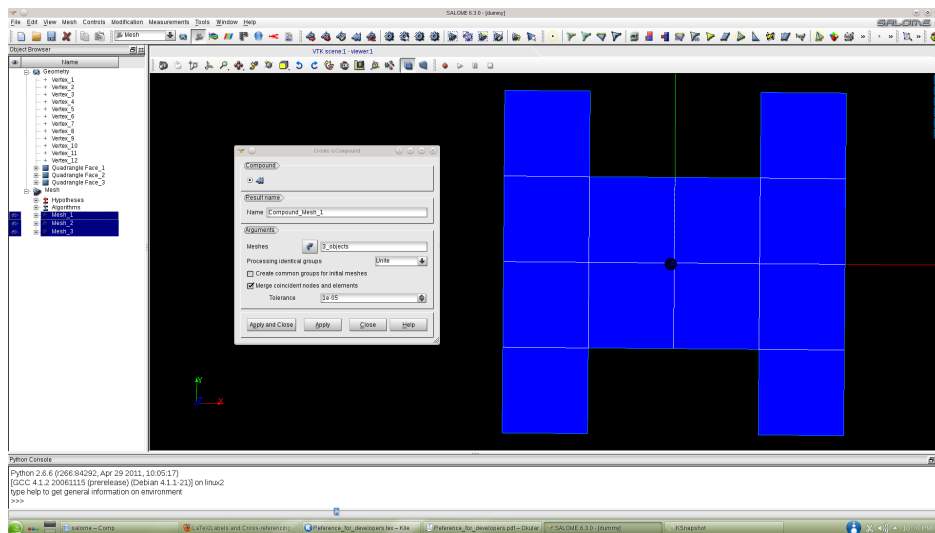


Figure 3.14

It is what we eventually have:

If you closely look at the picture above, you will see that some of the internal edges of the compound mesh still have the numbering. However, it is also strictly prohibited by the deal.II architecture !

- Therefore, the last step before exporting to the UNV format and deal.II library, is to manually remove all these internal numbers: **Modification** → **Remove** → **Elements**:

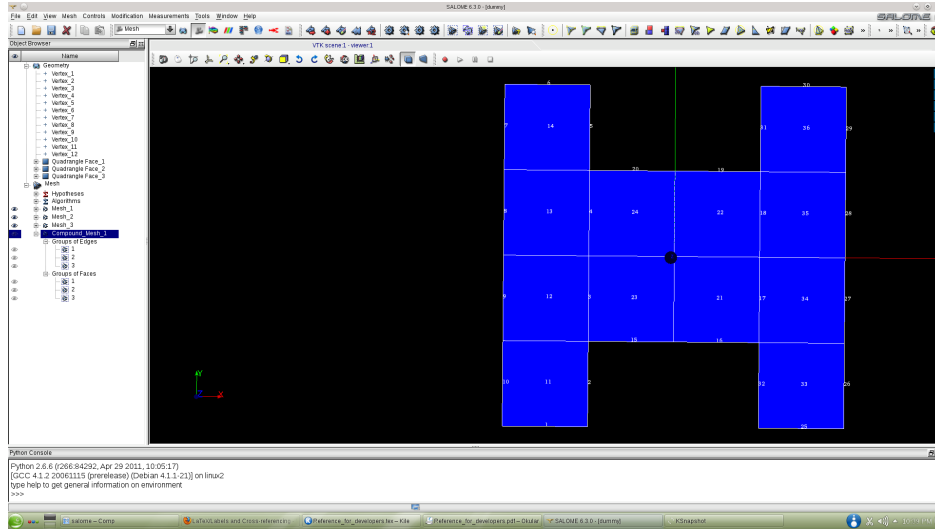


Figure 3.15

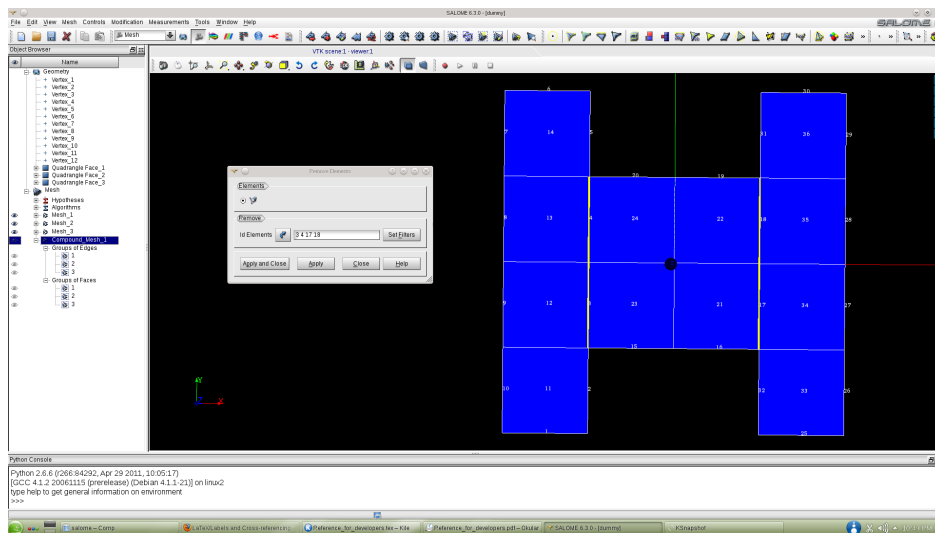


Figure 3.16

- The last step is **Ctrl+U** or **File → Export → UNV File**. Once we export the whole mesh into an UNV file, we can use it for the computational purposes (see the respective FCST tutorial).

3.2.2 Meshing with Hexotic

Hexotic is a fully automatic hexahedral mesh generator. It allows one to generate 3D meshes of complex geometries, without it we would be unable to mesh many things. Hexotic is a commercial piece of software, so users must activate it with a correct license key before they may use it - contact support@distine.com for more information. From experience it is often also necessary to use a proprietary 2D meshing algorithm from distine known as BLSURF.

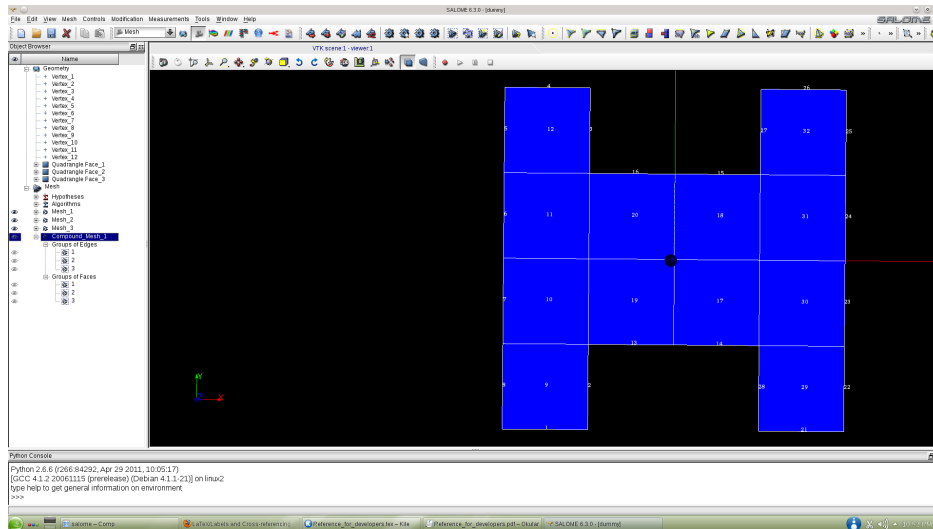


Figure 3.17

To mesh using Hexotic enter Salome’s meshing view. Select the 3d geometry you wish to mesh. From the drop down menu “Mesh” select “Create Mesh”. From the 3D menu select Hexotic. Hexotic parameters may be changed by editing the algorithm’s hypothesis. From the 2D menu select BLSURF. Notable parameters for the BLSURF algorithm that one may wish to edit in order to achieve a better fitting mesh are the Min and Max “Physical Size“ parameters.

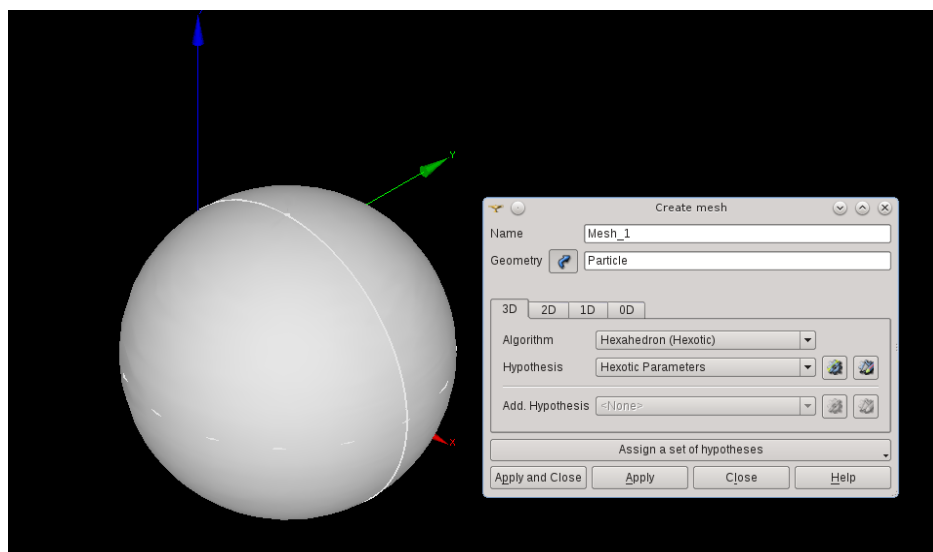


Figure 3.18: Meshing Dialogue Interface

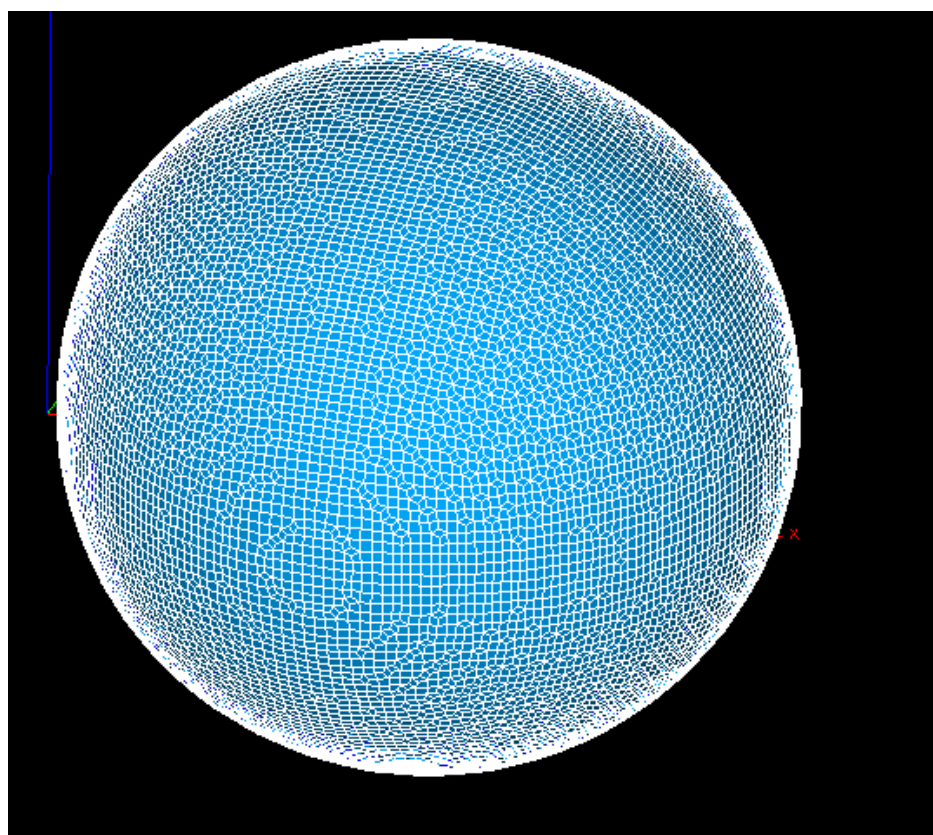


Figure 3.19: Mesh produced using Hexotic and BLSURF

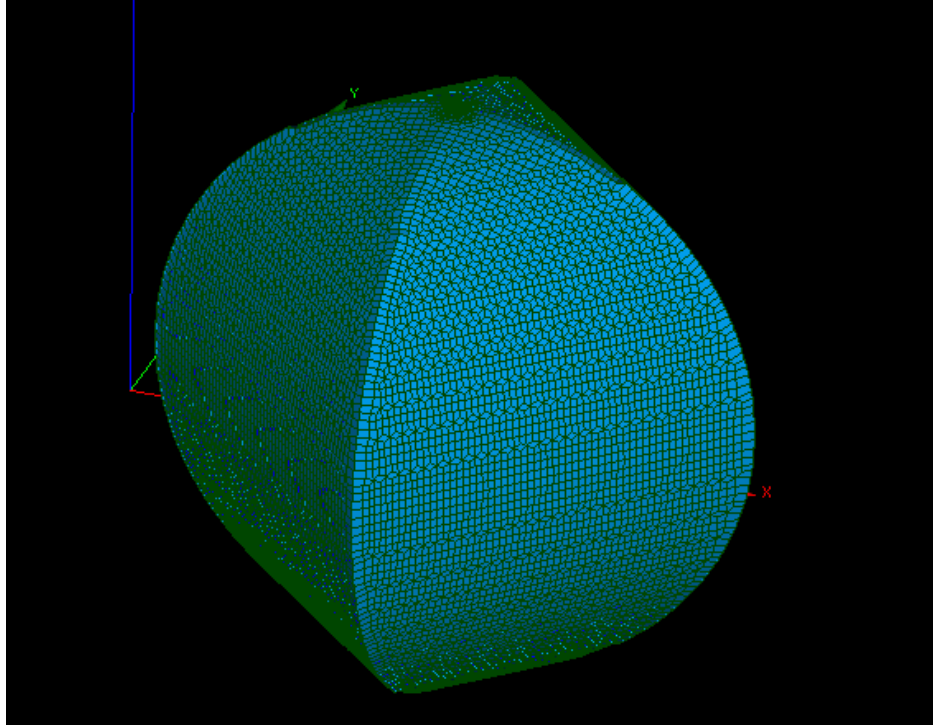


Figure 3.20: The same object as before, meshed using an inferior 2D algorithm.

3.3 Salome meshing using python scripts

3.3.1 Introduction

The previous section discussed meshing in Salome using the graphical user interface (GUI). This section will focus on creating and running scripts to create meshes and geometries. Reasons for using scripts instead of the GUI are as follows; improved repeatability of results, significant time saving due to automation, and removal of human error. Several Python scripts are included in the pre processing folder, they can be used to create various meshes of various geometries.

Meshing scripts are run through Salomes text user interface (TUI). Loading scripts can be done simply via the file drop down menu, load script. Meshing scripts are written in the Python programming language. Python is a very popular general purpose high level programming language. Unlike C++, Python code is not precompiled, but interpreted at run time by a Python interpreter. Some key features that make Python popular are it's simple yet elegant syntax, dynamic typing, automatic memory management, and large selection of freely available libraries. If you are interested in learning the Python programming language, Phil recommends [Dive Into Python](#).

3.3.2 Scripting Examples

```
1 import smesh, geompy, SMESH
2 import SALOMEDS
```

The above lines import the necessary Salome packages that will be required to create geometries and meshes. *smesh* is used for create python mesh objects, *geompy* is used for creating geometries. The other two packages contain constant flags. For more detail please see the following resources:

1. [smesh functions](#)
2. [geompy documentation](#)
3. [Salome TUI documentation](#)

The following simple example shows how to use geompy to create a simple geometry, and then mesh it using smesh.

```
1 def makeRectanglarMesh(self, width, height):
2
3     #Create vertices to describe rectangle
4     Vertex_1 = geompy.MakeVertex(dList[0], dList[1], dList[2])
5     Vertex_2 = geompy.MakeVertex(dList[0] + width, dList[1], dList[2])
6     Vertex_3 = geompy.MakeVertex(dList[0] + width, dList[1] + height, dList[2])
7     Vertex_4 = geompy.MakeVertex(dList[0], dList[1] + height, dList[2])
8
9     #Make rectangle geometries
10    rect = geompy.MakeQuad4Vertices(Vertex_1, Vertex_2, Vertex_3, Vertex_4)
11
12    #Create mesh object of rectangular geomtery
13    Mesh_1 = smesh.Mesh(rect)
14
15    #Set 1D meshing algorithm
16    Regular_1D = Mesh_1.Segment()
17    Local.Length.1 = Regular_1D.LocalLength(self.meshDensity)
18    Local.Length.1.SetPrecision(1e-07)
19
20    #Set 2D meshing algorithm
21    Mesh_1.Quadrangle()
22
23    #Compute and return
24    Mesh_1.Compute()
25    return Mesh_1
```

The following is an example of modifying meshes, and using mesh filters.

```
1 def delInternalEdges(self):
2     'This function deletes internal edges from self.compoundMesh'
3
4     #Create a search filter to find free borders of the mesh
5     search_filter = smesh.GetFilter(smesh.EDGE, smesh.FT_FreeBorders)
6     external_edges = self.compoundMesh.GetIdsFromFilter(search_filter)
7
8     #Get a list of all edges
9     all_edges = self.compoundMesh.GetElementsByType(SMESH.EDGE)
10
11    edges_to_remove = []
12
13    #The difference between the external_edges list and all_edges list will be the internal
14    #edges.
15    #The following loop iterates through the all_edges list, comparing it wil the
16    #external_edges list.
17
18    for b in all_edges:
```

```

17 | if b in external_edges:
18 |     pass
19 | else:
20 |     #The edge is internal, add it to the list of items to be removed from the mesh
21 |     edge_to_remove.append(b)
22 |
23 |     print "Removing internal edges:"
24 |     print edges_to_remove
25 |
26 |     #Remove the edges from the mesh
27 |     self.compoundMesh.RemoveElements(edges_to_remove)

```

When developing a new Python function for generating a geometry or mesh in Salome one may obtain a rough solution by:

1. Open the Salome GUI
2. Perform the necessary steps using the GUI to generate desire geometries and/or surfaces
3. Use the "Dump Study" facility, accessed from the File menu, this will produce a bulky but complete python program for the previously performed steps
4. Refine the script to the desired form

This is a very good method for obtaining an initial coding solution, or examples of correct code syntax and usage.

Chapter 4

Running FCST

4.1 Fuel Cell Analysis Using FCST

Analysis in FCST is the evaluation of a single data point on the polarization curve, it is usually carried out when quick evaluations are required. There are two files required when carrying out an analysis.

1. `main_app_param_file.prm`
2. `data_app_****.prm`

As this section is focused on how to run a simulation the details of these files will be further discussed in section 4.2. For now it is sufficient to know that `main_app_param` file is used to select the application you want to run (*cathode*, *MEA* ...) and the `data_app` file is used to hold all the parameters that describe the fuel cells physical properties (*Porosity*, *Platinum & Nafion Loading*, ...), dimensions, and operating conditions (*Relative Humidity*, *Temperature*, ...).

In order to run an analysis using FCST we need to open a terminal window on the desktop. Once this has been done we then need to navigate to the file that holds the `main_app_param` & `data_app` files of interest. In our example below we will run a simple MEA analysis. To do this we must go to the `mea` folder which is found in FCST's `data` folder. An illustration of this can be see below in image 4.1.

```
1 $~/fcst/data/mea/analysis/>
```

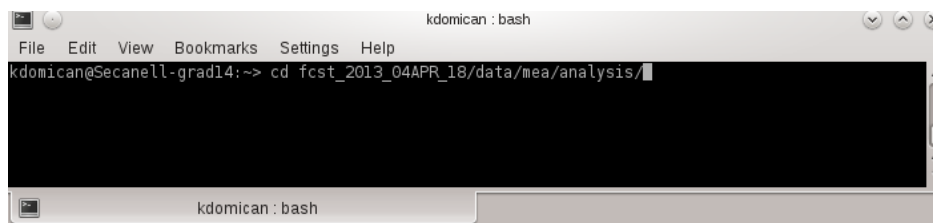


Figure 4.1: Terminal Window accessing MEA Analysis Model

Once the user has located the file of interest he/she is then required to “drill back” (`../..`) to the executable file (`fuel_cell-2d.bin`) located in the `lib` folder. An example of this can be seen in figure 4.2. Then finally hitting enter to run the code.

```
1 $~/fcst/data/mea/analysis> ../../../../lib/fuel_cell-2d.bin main_app-pemfc.prm
```

```

analysis : bash
kdomican@Secanell-grad14:~> cd fcst_2013_04APR_18/data/mea/analysis/
kdomican@Secanell-grad14:~/fcst_2013_04APR_18/data/mea/analysis> ../../lib/fuel_cell-2d.bin main_app_pemfc.prm

```

Figure 4.2: Terminal Window Drilling back to the executable file

In the above case as we are running the program in the `/fcst/data/mea/analysis`; therefore all the results will be outputted there.

FCST has several applications (See structure of the code below for details). By default, FCST solves the model of a fuel cell cathode (for the details on the model see M. Secanell et al., *Electrochimical Acta*, 52(7):2668-2682, February 2007). Sample input files to run this application are in `/data/cathode`.

Figure 4.3 illustrates the individual steps during a fuel cell analysis. This will be used as a building block later when looking at optimization in FCST.

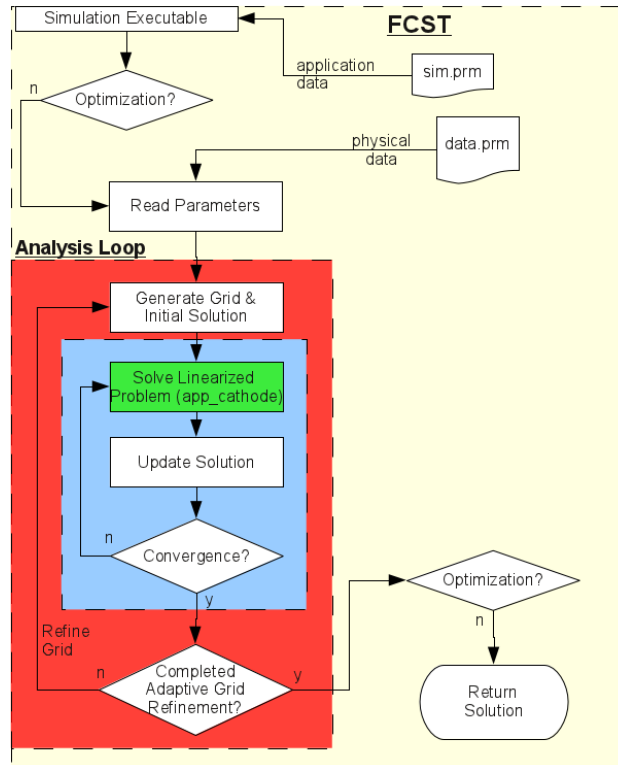


Figure 4.3: Schematic of Fuel Cell Analysis Code

4.2 Fuel Cell Parametric Study using FCST

When running a parametric study the user requires three files.

1. `main_app_param_file.prm`
2. `data_app_pemfc.prm`
3. `opt_app_parametric_default.prm`

4.2.1 Main Application File

1. `main_app_param_file.prm`

The `main_app_param_file.prm` is the initial file accessed by FCST. Its purpose is to:

- (a) Assign the application (*line 2*) being run. In this case, MEA (Note: This application corresponds to the application implemented in `./fcst/source/app_pemfc.cc` and `./fcst/include/app_pemfc.h`).
- (b) Informs FCST on the files to access for data & optimization/parametric information (*line 3 & 4*).
- (c) Assign the type of solver to use (*line 5*). In this case, a 3 point parabolic Newton method.
- (d) And lastly a Boolean command which tells FCST whether we are utilizing DAKOTA (*line 6*).

```
1 subsection Simulator
2   set simulator name = MEA
3   set simulator parameter file name = data_app_pemfc.prm
4   set optimization parameter file name = opt_app_parametric_default.prm
5   set solver name = Newton3ppC
6   set Dakota direct = true
7 end
```

The Application / Simulator Name: The application is the simulation that the user would like to run.

For example, if the user wants to run the cathode side of the fuel cell to test or observe recent changes and their effects, the user might run a `cathode` model. However if the user is looking to run the entire fuel cell (MEA), they would select (`MEA`) as seen above in line 2. A list of other application options can be found in `simulation_selector.cc`.

```
1 cathode | MEA | test_mesh | laplace | . . .
```

Solver Name: The `solver name` tells FCST the type of solver that will be used to carry out the evaluation. These solvers are inherited from `APPFRAME` found in the `contrib` folder. In our case we have specified `Newton3ppC` which is also the default solver, it uses a three point parabolic function in order to determine step size for the next evaluation point. For a list of additional solvers utilized by FCST see `simulation_selector.cc`.

```
1 Linear | NewtonBasic | Newton3ppC | Newton3pp | NewtonLineSearch
```

Dakota direct: When running a simple *analysis* case we will set this to false and FCST will carry out one evaluation run. If on the other hand we are running an optimization or in our case a parametric study which has multiple point evaluations, therefore “Dakota direct” will be set to **true**.

4.2.2 Data Application File

2. data_app_pemfc.prm

The `data_app_pemfc.prm` is a text file which is read by FCST in order to obtain the operating conditions and physical properties of the catalyst layer such as, Platinum & Nafion loading, porosity, and fuel cell dimensions. It also posses some instructions on the grid generation, adaptive refinement and how the output data should be formatted.

Note: The example below has been included to give the reader an idea of the structure of a typical data file, and some of the information contained.

```

1 #####
2 # $Id: $
3 #
4 # This file is used to simulate a PEM electrode with
5 # an agglomerate catalyst layer structure.
6 #
7 # Copyright (C) 2008–13, Marc Secanell, Peter Dobson and Kailyn Domican
8 #
9 #####
10
11 subsection Grid generation
12
13 set Type of mesh = PemfcMPL
14
15 set Initial refinement = 2
16 set Refinement = adaptive #global | adaptive
17 set Sort Cuthill–McKee = false
18 set Sort by component = true
19
20 #####
21 subsection Internal mesh generator parameters
22 #####
23 subsection Dimensions
24 set Cathode current collector width [cm] = 0.1 #[cm]
25 set Cathode channel width [cm] = 0.1 #[cm]
26 set Cathode CL thickness [cm] = 1.0e-3 #[cm]
27 set Cathode MPL thickness [cm] = 5.0e-3 #[cm]
28 set Cathode GDL thickness [cm] = 2.5e-2 #[cm]
29 set Membrane thickness [cm] = 0.25e-2 #[cm] #NRE211
30 set Anode CL thickness [cm] = 0.333e-3 #[cm]
31 set Anode MPL thickness [cm] = 5.0e-3 #[cm]
32 set Anode GDL thickness [cm] = 2.5e-2 #[cm]
33 set Anode current collector width [cm] = 0.1 #[cm]
34 set Anode channel width [cm] = 0.1 #[cm]
35 end
36 #####
37 subsection Material ID
38 set Cathode GDL = 2
39 set Cathode MPL = 3
40 set Cathode CL = 4
41 set Membrane = 5
42 set Anode CL = 6
43 set Anode MPL = 7
44 set Anode GDL = 8
45 end
46 #####

```



```

47     subsection Boundary ID
48         set c_Ch/GDL          = 2
49         set c_BPP/GDL         = 1
50         set c_GDL/CL          = 255
51         set c_GDL/MPL         = 255
52         set c_MPL/CL          = 255
53         set c_CL/Membrane     = 255
54         set Membrane/a_CL     = 255
55         set a_CL/GDL          = 255
56         set a_CL/MPL          = 255
57         set a_MPL/GDL         = 255
58         set a_GDL/BPP         = 3
59         set a_GDL/Ch          = 4
60     end
61 end
62 end
63
64 #####
65 subsection Adaptive refinement
66     set Number of Refinements = 3                # (default)
67     set Output initial solution = true            # (default) false
68     set Output intermediate solutions = true      # (default) true
69     set Output intermediate responses = true      # (default) true
70     set Output final solution = true              # (default) true
71     set Output solution for transfer = true       # (default) false
72     set Read in initial solution from file = true # (default) true
73 end
74
75 #####
76 #####
77 subsection System management
78
79     set Number of solution variables = 5
80
81     subsection Solution variables
82         set Solution variable 1 = oxygen_molar_fraction
83         set Solution variable 2 = water_molar_fraction
84         set Solution variable 3 = protonic_electrical_potential
85         set Solution variable 4 = electronic_electrical_potential
86         set Solution variable 5 = membrane_water_content
87     end
88
89     subsection Equations
90         set Equation 1 = Ficks Transport Equation - oxygen
91         set Equation 2 = Ficks Transport Equation - water
92         set Equation 3 = Proton Transport Equation
93         set Equation 4 = Electron Transport Equation
94         set Equation 5 = Membrane Water Content Transport Equation
95     end
96
97 end
98 #####
99 #####
100 subsection Discretization
101     set Element = FESystem[FE_Q(2)^5] #System of 5 fe
102     set Boundary fluxes = false
103     set Interior fluxes = false
104
105     subsection Matrix
106         set Quadrature cell = -1
107         set Quadrature face = -1
108     end
109
110     subsection Residual
111         set Quadrature cell = -1

```

```

112     set Quadrature bdry = -1
113     set Quadrature face = -1
114 end
115 end
116 #####
117 #####
118
119 #####
120 subsection Newton
121     set Debug residual      = false
122     set Debug solution      = false
123     set Debug update        = false
124     set Max steps           = 100
125     set Reduction           = 1.e-12
126     set Tolerance           = 1.e-9
127 end
128
129 #####
130 subsection Fuel cell data
131
132 #####
133 subsection Operating conditions
134     set Temperature cell = 353          # [K] #
135     set Cathode pressure = 101325        # [Pa] # 101325 (1.0 atm) |
136     set Cathode relative humidity = 0.7  # [%] #
137     set Anode pressure = 101325          # [Pa] # 101325 (1.0 atm) |
138     set Anode relative humidity = 0.7    # [%] #
139     set Voltage cell = 0.6               # [V] #
140 end
141 #####
142
143 #####
144 subsection Cathode gas diffusion layer
145
146     set Material id = 2
147     set Gas diffusion layer type = DesignFibrousGDL # DummyGDL | SGL24BA
148
149     subsection DesignFibrousGDL # DummyGDL | SGL24BA
150         ##### Composition: #####
151         set Porosity = 0.6
152         ##### Gas transport #####
153         ## Anisotropy
154         set Anisotropic transport = true # (default) false
155         set Method effective transport properties in pores = Tomadakis # (default)
156             Bruggemann | Given | Percolation | Tomadakis | Mezedur
157         set Method effective transport properties in solid = Percolation # (default)
158             Bruggemann | Given | Percolation
159         ## XX
160         set Porosity threshold X = 0.11 # (default) 0.12 | 0.118 (Peters Thesis) |
161             0.11
162         set Porosity network constant X = 0.785 # (default) 2.0 | 0.785 (Peters
163             Thesis) [Page 69]
164         set Porosity gamma network constant X = 0.0 # (default) 0.0 |
165         #
166         set Electrical conductivity X = 16.03 # [S/cm]
167         set Solid network threshold X = 0.0 # (default) 0.12 |
168         set Solid network constant X = 1.5 # (default) 2.0 |
169         ## YY
170         set Porosity threshold Y = 0.11 # (default) 0.12 | 0.118 (Peters Thesis) |
171             0.11
172         set Porosity network constant Y = 0.521 # (default) 2.0 |
173         set Porosity gamma network constant Y = 0.0 # (default) 0.0 |
174         #
175         set Electrical conductivity Y = 272.78 # [S/cm]
176         set Solid network threshold Y = 0.0 # (default) 0.12 |

```

```

172     set Solid network constant Y = 1.0          # (default) 2.0 |
173 end
174 end
175 #####
176 subsection Cathode microporous layer
177     set Material id = 3
178     set Micro porous layer type = DesignMPL      # (default) SGL24BC | DesignMPL
179     subsection DesignMPL
180         set Porosity = 0.4                      # From experimental data (manufacturers data) on
181         Sigracel 24BC
182         set Anisotropic transport = false
183         ##### Pore network #####
184         set Method effective transport properties in pores = Percolation
185         set Porosity threshold = 0.118
186         set Porosity network constant = 2.0
187         ##### Solid network #####
188         set Method effective transport properties in solid phase = Percolation
189         set Electric conductivity = 88.84        # From experimental data (manufacturers
190         data) on Sigracel 24BC
191         set Solid network threshold = 0.118
192         set Solid network constant = 2.0
193     end
194 end
195 #####
196 subsection Cathode catalyst layer
197     set Material id                                = 4
198     set Catalyst layer type                        =
199     HomogeneousCL #[ DummyCL | AgglomerateCL | HomogeneousCL ]
200
201     set Catalyst type                                = Platinum
202     set Catalyst support type                        = Carbon Black
203     set Electrolyte type                            = Nafion
204     set Kinetics type                                =
205     TafelKinetics
206
207 #####
208 subsection Materials
209     ##
210     subsection Nafion
211         set Henrys Law Constant for Oxygen [Pa cm3/mol] = 3.1664e10
212         set Henrys Law Constant for Hydrogen [Pa cm3/mol] = 6.69e10
213         set Method to compute proton conductivity = NRE211
214         set Method to compute water diffusion = Motupally
215         set Electro-osmotic drag method = Constant
216         set Electro-osmotic drag coefficient = 1.0
217         set Method for sorption isotherm = Hinatsu
218         set Method to compute enthalpy of sorption of water = Constant
219         set Enthalpy of sorption of water [J/mol] = 45000.0
220         set Oxygen diffusion coefficient [cm2/s] = 9.726e-6 # 9.726e-6 (
221         Peters Thesis)
222     end
223     ##
224     subsection Platinum
225         set Cathodic transfer coefficient (ORR) = 1.0 # 1.0 (Tafel
226         Kinetics)
227         set Oxygen reaction order (ORR) = 1.0
228         set Reference exchange current density (ORR) [uA/cm2] = 2.47e-2
229         set Reference oxygen concentration (ORR) = 0.725e-5 # 0.725e-5 (
230         Tafel)
231         # set Method for kinetics parameters (ORR) = Parthasarathy
232     end
233     ##
234     subsection Carbon Black

```

```

230     set Electrical conductivity [S/cm] = 88.84
231     set Density [g/cm^3] = 1.25 # (default) 2.0 | 1.25 fit to General
      Motors data. With Modified Porosity threshold = 0.25884
232   end
233 end
234
235 ##
236 subsection ConventionalCL
237     set Platinum loading on support (%wt) = .46 # 0.2 (ESDLab Ultra-
      thin CL) # 0.46 (Conventional CL) # 0.5 (GM)
238     set Platinum loading per unit volume (mg/cm3) = 400 # 400 (GM estimated
      width = .001[cm]) # 147.05 (ESDLab Ultra-thin width 0.00017 [cm]) # 125.0 (
      ESDLab Ultra-thin width 0.0002[cm] [ 125 = m.Pt/Cathode CL thickness])
239     set Electrolyte loading (%wt) = 0.30 # 0.2 | 0.3 | 0.4 |
      0.5 (ESDLab testing)
240     set Active area [cm^2/cm^3] = 2.0e5 # 2.0e5 (original) #
      0.2, 67462.5 | 0.3, 42987.5 | 0.4, 62500 | 0.5, 60750 (ESDLab Ultra-thin CL
      )
241     ##### Pore network #####
242     set Method effective transport properties in pores = Percolation
243     set Porosity threshold = 0.3 # 0.3 (Peters Thesis)
      # 0.118 | 0.25884 (Carbon Density = 1.25 [GM fitted])
244     set Porosity network constant = 4.0 # 4.0 (Peters Thesis)
      # 2.0
245     set Porosity gamma network constant = 0.0
246     ##### Solid network #####
247     set Method effective transport properties in solid phase = Percolation
248     set Solid network threshold = 0.118
249     set Solid network constant = 2.0
250     ##### Ionomer network #####
251     set Method effective transport properties in electrolyte phase = Percolation #
      Bruggemann | Iden11 | Percolation | mesh_structure | Iden09
252     set Electrolyte network threshold = 0.0
253     set Electrolyte network constant = 2.0
254   end
255 ##
256 subsection AgglomerateCL
257     set Agglomerate composition = ionomer
258     set Agglomerate type = spherical
259     set Agglomerate solver = analytical
260     set Average current in cell = false
261     set Radius of the agglomerate [nm] = 100
262     set Agglomerate porosity = 0.3
263   end
264 end
265
266 #####
267 subsection Membrane layer
268     set Material id = 5
269
270     set Membrane layer type =
      NafionMembrane
271
272     set Electrolyte type = Nafion
273   #####
274   subsection Materials
275     subsection Nafion
276     set Henrys Law Constant for Oxygen [Pa cm^3/mol] = 3.1664e10
277     set Henrys Law Constant for Hydrogen [Pa cm^3/mol] = 6.69e10
278     set Method to compute proton conductivity = NRE211
279     set Method to compute water diffusion = Motupally
280     set Electro-osmotic drag method = Constant
281     set Electro-osmotic drag coefficient = 1.0
282     set Method for sorption isotherm = Hinatsu
283     set Method to compute enthalpy of sorption of water = Constant

```

```

284         set Enthalpy of sorption of water [J/mol]                = 45000.0
285     end
286 end
287 end
288
289 #####
290 subsection Anode catalyst layer
291
292     set Material id = 6
293
294     set Catalyst layer type = HomogeneousCL    #[ DummyCL | AgglomerateCL |
        HomogeneousCL ]
295
296     set Catalyst type                                = Platinum
297     set Catalyst support type                        = Carbon Black
298     set Electrolyte type                            = Nafion
299     set Kinetics type                                =
        DualPathKinetics
300 #####
301 subsection Materials
302     subsection Platinum
303         #set Method for kinetics parameters (HOR)                = DualPathKinetics    #
        Required for Wangs Kinetics, rest parameters automatically calculated
304         set Reference hydrogen concentration (HOR)                = 0.59e-6            #
        Required for Dual Path Kinetics, rest parameters automatically calculated
305     end
306     subsection Carbon Black
307         set Density [g/cm^3]                                    = 1.25                #
        GM data
308     end
309     subsection Nafion
310         set Henrys Law Constant for Oxygen [Pa cm^3/mol]        = 3.1664e10
311         set Henrys Law Constant for Hydrogen [Pa cm^3/mol]      = 6.69e10
312         set Method to compute proton conductivity              = NRE211
313         set Method to compute water diffusion                  = Motupally
314         set Electro-osmotic drag method                        = Constant
315         set Electro-osmotic drag coefficient                    = 1.0
316         set Method for sorption isotherm                        = Hinatsu
317         set Method to compute enthalpy of sorption of water     = Constant
318         set Enthalpy of sorption of water [J/mol]              = 45000.0
319     end
320 end
321 #####
322 subsection ConventionalCL
323     set Platinum loading on support (%wt) = .46                # 0.2 (ESDLab Ultra-thin CL)
        # 0.46 (Conventional CL)
324     set Platinum loading per unit volume (mg/cm3) = 400        # 400 (GM estimated width
        = .001[cm]) # 147.05 (ESDLab Ultra-thin width 0.00017 [cm]) # 125.0 (ESDLab
        Ultra-thin width 0.0002[cm] [ 125 = m.Pt/Cathode CL thickness])
325     set Electrolyte loading (%wt) = 0.30
326     set Active area [cm^2/cm^3] = 2.0e5                        # 1.2e5 (Experimental) | 0.3
        Nafion, 42987.5 (ESDLab Ultra-thin CL) | 2.0e5
327     ##
328     set Method effective transport properties in pores = Percolation
329     set Porosity threshold = 0.3
330     set Porosity network constant = 4.0                        # 4.0 (Peters Thesis) | 2.0
331     set Porosity gamma network constant = 0.0
332     ##
333     set Method effective transport properties in solid phase = Percolation
334     set Solid network threshold = 0.118
335     set Solid network constant = 2.0
336     ##
337     set Method effective transport properties in electrolyte phase = Percolation
        # Bruggemann | Iden11 | Percolation *| mesh-structure | Iden09
338     set Electrolyte network threshold = 0.0

```

```

339     set Electrolyte network constant = 2.0
340 end
341 ##
342 subsection AgglomerateCL
343     set Agglomerate type = spherical
344     set Radius of the agglomerate [nm] = 100
345 end
346
347 end
348
349 #####
350 subsection Anode microporous layer
351     set Material id = 7
352     set Micro porous layer type = DesignMPL      # (default) SGL24BC | DesignMPL
353     subsection DesignMPL
354         set Porosity = 0.4                        # From experimental data (manufacturers data)
355         on Sigracel 24BC
356         set Anisotropic transport = false
357         set Electric conductivity = 88.84        # From experimental data (manufacturers
358         data) on Sigracel 24BC | 5.09
359         ##### Pore network #####
360         set Method effective transport properties in pores = Percolation
361         set Porosity threshold = 0.118
362         set Porosity network constant = 2.0
363         ##### Solid network #####
364         set Method effective transport properties in solid phase = Percolation
365         set Solid network threshold = 0.118
366         set Solid network constant = 2.0
367     end
368 end
369 #####
370 subsection Anode gas diffusion layer
371
372     set Material id = 8
373
374     set Gas diffusion layer type = DesignFibrousGDL  # DummyGDL | SGL24BA
375
376     subsection DesignFibrousGDL      # DummyGDL | SGL24BA
377         ##### Composition: #####
378         set Porosity = 0.6
379         ##### Gas transport #####
380         ## Anisotropy
381         set Anisotropic transport = true
382         set Method effective transport properties in pores = Tomadakis
383         set Method effective transport properties in solid = Percolation
384         ## XX
385         set Porosity threshold X = 0.11          # 0.118 (Peters Thesis) | 0.11
386         set Porosity network constant X = 0.785
387         set Porosity gamma network constant X = 0.0
388         #
389         set Electrical conductivity X = 16.03    # [S/cm]
390         set Solid network threshold X = 0.0
391         set Solid network constant X = 1.5
392
393         ## YY
394         set Porosity threshold Y = 0.11          # 0.118 (Peters Thesis) | 0.11
395         set Porosity network constant Y = 0.521
396         set Porosity gamma network constant Y = 0.0
397         #
398         set Electrical conductivity Y = 272.78   # [S/cm]
399         set Solid network threshold Y = 0.0
400         set Solid network constant Y = 1.0
401     end
402 end

```

```

402| #####
403| # END Fuel cell data
404| end
405|
406| #####
407| #####
408| subsection Output Variables
409|   set num_output_vars = 1
410|   set Output_var_0 = cathode_current
411| end
412|
413| #####
414| subsection Output
415|   subsection Data
416|     set Output format = vtk
417|   end
418|   subsection Grid
419|     set Format = gnuplot      # eps # xfig
420|   end
421| end

```

(a) Grid generation (*line 11-62*)

Type of mesh In the grid generation subsection the user is required to first specify the type of grid to be assigned to the simulation. Below is a list of possible options.

```

1| GridExternal | Cathode | Anode | CathodeMPL | Pemfc | PemfcMPL | Agglomerate_CL

```

Once the ‘Type of mesh’ has been specified the user then indicates the number of initial refinements to be carried out (*line 15*). Figures 4.4, 4.5, & 4.6, illustrates a general refinement process. The refinement process can also be specified as **Global** or **Adaptive** (*line 16*). During adaptive refinement the sections that show the largest relative error will be further refined (As seen on the left hand side of Figure 4.7)

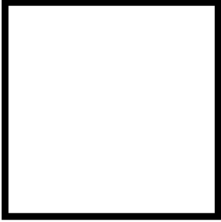


Figure 4.4: Initial Grid

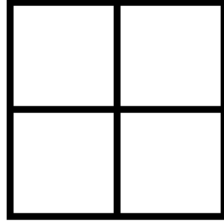


Figure 4.5: Grid 1st Refinement

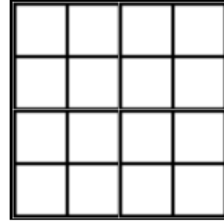


Figure 4.6: Grid 2nd Refinement

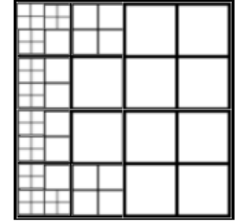


Figure 4.7: Grid Adaptive Refinement

GridExternal If the **GridExternal** option has been chosen the user is then also required to add the following lines to inform FCST as to where to obtain the unique grid.

```

1| set Type of mesh = GridExternal
2| set File name = test.unv      # Name of the mesh file
3| set File type = UNV          # Meshtype (see deal.ii supported mesh types)

```

i. Internal mesh generator parameters

This section is responsible for specifying:

- A. Dimensions (GDL, Cathode,& Anode thicknesses ...)
- B. Material ID
- C. Boundary ID

(b) **Adaptive refinement** (*line 65-73*)

The user can also define the outputs (initial,intermediate solutions/responses, & final solutions) during the refinement steps.

The ‘Output solution for transfer’ option, will produce a hidden file containing the current solution values. This solution can then be read in if ‘Read in initial solution from file’ is set to true.

The ‘Read in initial solution from file’ option gives the user the ability to read in previously obtained solutions. This is very beneficial when convergence becomes an issue.

Note: It is advised to have both ‘Output solution for transfer’ & ‘Read in initial solution from file’ set to true as it can improve convergence rates.

(c) **System management** (*line 77-97*)

The system management subsection is responsible for defining the **Solution variables & Equations** being used.

The current available variable options are:

- i. X_{O_2} (Oxygen Molar Fraction)
- ii. X_{H_2O} (Water Molar Fraction)
- iii. ϕ_m (Protonic Electrical Potential)
- iv. ϕ_s (Electronic Electrical Potential)
- v. λ (Membrane Water Content)
- vi. T_{solid} (Temperature of Solid Phase) [Available in future releases]

(d) **Discretization** (*line 100-115*)

The **Discretization** section defines the order of the solver for the variables being solved for.

- i. X_{O_2} (Oxygen Molar Fraction)
- ii. X_{H_2O} (Water Molar Fraction)
- iii. ϕ_m (Protonic Electrical Potential)
- iv. ϕ_s (Electronic Electrical Potential)
- v. λ (Membrane Water Content)

Above in our example we have the following line (*line 101*)

```
1 set Element = FESystem[FE_Q(2)^5]
```

Where;

- $FE_Q(2)$ refers to the order of the solver in our case quadratic. This can also take any integer form 1-6.
- $FE_Q(2)^5$. 5 refers to the number of variables included in the quadratic category.
For example, if we wanted to have the first two elements(X_{O_2}, X_{H_2O}) solved cubically and the last three (ϕ_m, ϕ_s , & λ) solved linearly we would insert the following line.

$$FESystem[FE_Q(3)^2 - FE_Q(1)^3]$$

The final two sections in System management are:

- i. **Matrix**
- ii. **Residual**

These subsections control the number of quadrature points required to evaluate the integrals in the local weak form of our partial differential equation. The default value of -1 will set the number of quadrature points to the order of the finite element used plus one in each direction, e.g. for second order elements, no. of quadrature points in each direction is $= 2 + 1 = 3$ (In 2D, using quadratic elements, the number of quadrature points would be 9). Assigning a default value of -1, for most cases, would be sufficient to achieve an exact solution of the integrals.

(e) **Newton** (*line 120-127*)

Required to provide information to the Newton solver.

- Debug residual
- Debug solution
- Debug update

The above debug options prints out the intermediate values for the residuals, solutions and the updates. This then can be used to locate errors/bugs in the code.

- Max steps
Used to limit the number iterations carried out by the Newton solver.
- Reduction
- Tolerance

Tolerance defines the decimal place accuracy of the Newton solver. Ideally this tolerance should be kept at $1.0e^{-9}$. However, in certain circumstances convergence at these tolerance may not be possible or feasible given the computational time. In these scenarios it is possible to reduce the tolerance to $1.0e^{-4} - 1.0e^{-6}$ while still keeping reasonable accuracy.

(f) **Fuel cell data** (*line 130-403*)

In the Fuel cell data subsection all relevant properties pertaining to each respective layer and the operating conditions are specified.

- i. **Operating conditions** (*line 133-140*)
- ii. **Cathode gas diffusion layer**

A variety of gas diffusion layers may be chosen from. The current available options are:

- A. **DesignFibrousGDL**
- B. **DummyGDL**
- C. **SGL24BA**

When changing between gas diffusion layers type (line 147 [cathode] & 372 [anode]) it is also required to change lines 149 [cathode] & 374 [anode], and the respective properties specific to the gas diffusion layer chosen.

- iii. **Cathode microporous layer**

A variety of micro-porous layers may be chosen from. The current available options are:

- A. **DesignMPL**
- B. **SGL24BC**

When changing between micro-porous layers type (line 178 [cathode] & 352 [anode]) it is also required to change lines 179 [cathode] & 353 [anode], and the respective properties specific to the micro-porous layer chosen.

iv. Cathode catalyst layer

A variety of catalyst layers may be chosen from. The current available options are:

- A. DummyCL
- B. HomogeneousCL
- C. AgglomerateCL

v. Membrane layer

- A. Materials (Nafion)

vi. Anode catalyst layer

A variety of Catalyst layers may be chosen from. The current available options are:

- A. DummyCL
- B. HomogeneousCL
- C. AgglomerateCL

vii. Anode microporous layer

A variety of micro-porous layers may be chosen from. The current available options are:

- A. DesignMPL
- B. SGL24BC

viii. Anode gas diffusion layer

A variety of gas diffusion layers may be chosen from. The current available options are:

- A. DesignFibrousGDL
- B. DummyGDL
- C. SGL24BA

(g) Output Variables (*line 408*)

In this section it is possible to specify the number of output variables. In our above example we are only outputting one variable however if we are interested in printing additional variable onto the terminal screen we add the following format to the parameter file.

```
1 subsection Output Variables
2   set num_output_vars = 3
3   set Output_var_0 = cathode_current
4   set Output_var_0 = water_cathode
5   set Output_var_0 = anode_current
6 end
```

The remaining **Output Variables** subsections are used to specify the file format.

- i. Data
- ii. Grid

Additional sections of the data file have been continued here in order to give the reader an idea of good coding practices and the benefits of following these guidelines.

Cathode microporous layer: Below we can see that for the data file the values for porosity and electric conductivity are supported by a short piece of text specifying where these values have been obtained from.

```

1 subsection Cathode microporous layer
2   set Porosity = 0.4 # 0.4 (Manufacturers Data) on Sigracel 24BC
3   ##### Solid network #####
4   set Electric conductivity = 88.84 # 88.84 (Manufacturers Data) on Sigracel 24BC
5 end

```

Materials: Another example of this can be seen in the Materials section. We should note that the **Method to compute proton conductivity** has information on the default option and also the other options available to the user. We can also see that the **Oxygen diffusion coefficient** value has also been referenced to Peter Dobson's thesis (2011).

```

1 subsection Materials
2   subsection Nafion 1100
3     set Henrys Law Constant for Oxygen [Pa cm^3/mol] = 3.1664e10
4     set Method to compute proton conductivity = NRE211 # (default) NRE211 | Constant
5     set Oxygen diffusion coefficient [cm^2/s] = 9.726e-6 # 9.726e-6 (Peters Thesis ,
6       2011)
7   end

```

The benefits of this type of text formatting is;

- The user is able to see what methods are available without having to search the code. Also if the user knows they are not going to change the method or values from the default (*which is easily on view*) it allows them to delete the text from their own personal file.

The advantages of this is a reduced text file allowing the user to navigate more easily and a reduction in the probability of accidentally changing methods or variables located under different subsections.

- The user can now locate the referenced data to check whether that values is acceptable under the data files operating conditions. However this is not easily done if the value has not been referenced.

This is not a major issue if the person who has implemented the value still remains contactable, however if they are not it is a timely procedure in gaining the relevant information (*Providing contact information is still correct*)

- By incorporating the reference text it ensures redundancy on the values. During the process of changing the data file sometimes keys on the keyboard can be accidentally hit causing a change to one of the values. The value will then go unnoticed if the effects are small. This can cause problems with the codes results later and will require the user to go through each value checking them individually. However if the reference text is available with the original value, it decreases the scrutiny time greatly and reduces the chance of errors entering the text files.

4.2.3 Parameter/Optimization Application File

3. opt_app_parametric_default.prm

The `opt_app_parametric_default.prm` is used when carrying out parametric studies.

```

1 #####
2 #
3 # This file is used to run a multi-dimensional parametric study.
4 # See end of file for list of possible design variables.
5 #

```

```

6 #####
7
8 subsection Optimization Parameters
9
10 ##### NOTE THAT THIS SECTION ONLY EXISTS WHEN RUNNING IN OPTIMIZATION MODE #####
11 #####
12 subsection Optimization Program Options
13     set Use dakota input file = false # (default) false
14     set Dakota_Input_File = dakota_input.in # not needed if -Use dakota input
15         file = false-
16
17     set Optimization method = multidim_parameter_study # multidim_parameter_study |
18         optpp-q-newton | nl2sol | ncsu-direct
19
20 end
21
22 subsection Design Variables
23     set num_design_variables = 1 # 2
24     set DV_0_name = V_cell # P_cell
25     set DV_1_name = T_cell # P_c | RH_a
26     set DV_2_name = prc_Pt_c # RH_c | prc_Pt_c
27
28 ##### Lower Bound #####
29 ##### lb < -1e30 for -inf #####
30 #-----#
31
32 set DV_0_lb = -1.1 # V # Changed to -1.1, force dekota to start at -1.1
33 set DV_1_lb = 303 # K #
34 set DV_2_lb = 0.2 # % #
35
36 ##### Upper Bound #####
37 ##### ub > 1e30 for inf #####
38 #-----#
39
40 set DV_0_ub = -0.1 # V #
41 set DV_1_ub = 353 # K #
42 set DV_2_ub = 0.5 # % #
43
44 ##### Parameter Study Partitions #####
45 ##### NOTE: Evaluated at n+1 points between lower and upper bound #####
46 #####
47
48 set DV_0_partition = 50
49 set DV_1_partition = 8
50 set DV_2_partition = 10
51 end
52
53 subsection Responses
54     set num_objectives = 1
55     set num_nl_constraints = 0 # (default) 0
56     set num_eq_constraints = 0 # (default) 0
57
58     set RESP_0_name = current
59     end
60 end

```

Located at the bottom of all `opt_app` files in both parametric & optimization is a list of design variables available for the user to carry out a parametric studies or optimization. As of **1-SEP-2013** the following table lists the current parameters that can be passed to DAKOTA for parametric studies/optimization.

If the user requires additional variables for parametric/optimization studies, modification of the `dakota_application.cc` file should be carried out.

```

1 ##### List of Possible Design Variable Names #####
2 #####
3 # // Conventional_CL.cc

```

```

4 # V_Pt_c | V_Pt_a // Platinum loading per unit volume [mg/cm3] (Cathode | Anode)
5 # prc_Pt_c | prc_Pt_a // Platinum loading on support [%wt] (Cathode | Anode)
6 # prc_N_c | prc_N_a // Electrolyte loading [%wt] (Cathode | Anode)
7 # Av_c | Av_a // Active area [cm^2/cm^3] (Cathode | Anode)
8
9 # // Agglomerate_CL.cc
10 # r_agg_c | r_agg_a // Radius of the agglomerate [nm] (Cathode | Anode)
11 # r_agg // Radius of the agglomerate [nm] **possibly redundant**
12 # epsilon_agg_c | epsilon_agg_a // Agglomerate porosity (Cathode | Anode)
13 # epsilon_agg // Agglomerate porosity **possibly redundant**
14
15 # // Operating_Conditions.cc
16 # V_cell // Cell Voltage
17 # T_cell // Cell Temperature
18 # dV_a // Voltage drop in the Anode
19 # P_c | P_a // Pressure (Cathode | Anode)
20 #
21 # RH_c | RH_a // Relative Humidity (Cathode | Anode)
22 # OCV // Open Circuit Voltage
23
24 # // Geometries.cc
25 # L_CCL | L_ACL // CL thickness (Cathode | Anode)
26 # L_CGDL | L_AGDL // GDL thickness (Cathode | Anode)
27 # L_CMPL | L_AMPL // MPL thickness (Cathode | Anode)
28 # Ch_width // Channel Width (Cathode | Anode)

```

Optimization Program Options: The Optimization Program Options of the `opt_app` parametric file is responsible for telling FCST whether it is required to formulate its own `dakota_input.in` file or if you are supplying DAKOTA with a predefined input file (*line 13 & 14*).

“Use dakota input file” & “Dakota_Input_File”: If `Use dakota input file` is set to `false` then FCST will pass on the information specified in the `opt_app-parametric.default.prm` file and DAKOTA will print out a new `dakota_input.in` at run time. If however it is set to `true` we are telling FCST that we have already specified an input file and that DAKOTA should use this directly rather than reading the information from the rest of the `opt_app` file.

Note: For completeness ‘‘Use dakota input file’’ & ‘‘Dakota_Input_File’’ have been included in the default parametric file, however, when the user is not using their own `dakota_input.in` file both line 13 & 14 can be deleted.

Given that in most cases the user specifies all the parametric & optimization information in the `opt_app` file. The following descriptions will be relevant for cases when `Use dakota input file = false`.

Optimization Method: The `Optimization method` command is used to specify the type of study that is being carried out (optimization, parametric study, least squares fit, ...) for additional information on `Optimization methods` see section 4.3. In our case we are looking to carry out a parametric study so the `multidim_parameter_study` should be specified.

Design Variables: In the design variables section (*line 19-45*) we specify the number of design variables that we want to change (*line 20*), the upper and lower bounds for that variable (*line 25-37*), and the number of points that we want to evaluate between the upper and lower bounds (*line 39-45*).

num_design_variables: In the example above we have specified one design variable `V_cell` for a single parametric study. The corresponding upper, lower bounds, and partitions can be found at line 28, 35, and 42.

If the user wants to conduct a multi-dimensional parametric study we would simply change `num_design_variables` value from one to whatever number of variables required. In the example about we have the capabilities of increasing the number of variables to three. If the user requires more variables than this the user can simply add additional `DV_#_name` and the corresponding upper, lower bound and partitions.

Note: The upper and lower bound of the voltage have been set to negative. This is because DAKOTA will vary its parameters from the lowest value to the highest value (In the non-negative case this is from 0.1 - 1.1 [V]).

During the solving process FCST uses the last mesh data and node values as the initial starting point for the next point evaluation. As the function evaluations become more difficult as we enter the mass transport region (`V_cell` of 0.3 - 0.1) the time taken to evaluate these points is much longer. If we change the voltage values to their negative the parametric study will go from 1.1 to 0.1 [V], this in turn decreases the solving time and allows the solver to use the previous values as appose to starting at the 0.1 [V] (the most difficult case).

Additional advantages as well as reduced time is that in some cases if the solver begins at lower voltages (e.g. 0.1 [V]) the solver is unable to to converge due to the low oxygen values however if the solver starts at the 'easier case' (high voltages 1.1 - 0.8 [V]) it will carry on the previous solutions and be able to converge at the lower voltages.

Responses: The response section of the `opt_app` parametric file, specifies the number of outputs desired in the `dakota.tabular.dat` data file, in our case there is ONLY ONE objective value (*Current Density* [A/cm²]) line 52.

It also is responsibly for specifying the type and number of constraints. There are two types of constraints; Equality (*line 49*) and Inequality (*line 50*), in general we do not typically use constraints in parametric studies so this section will be covered in more detail in the **optimization section**.

4.3 Optimization using FCST

When running an Optimization study the user requires three files, as seen above with parametric studies. The only difference however is that we change out(*alter*) the third file to an optimization file/format.

`opt_app_optimization_default.prm`

```

1 #####
2 #
3 # This file is used to run the optimization interface.
4 # See end of file for a list of optimization variables.
5 #
6 #####
7
8 subsection Optimization Parameters
9
10 ##### NOTE THAT THIS SECTION ONLY EXISTS WHEN RUNNING IN OPTIMIZATION MODE #####
11 #####
12 subsection Optimization Program Options
13     set Use dakota input file = false # (default) false
14     set Dakota_Input_File = dakota.input.in
15
16     set Optimization strategy = single-method # single-method | multi_start |
17     pareto_set | hybrid
18     set Optimization method = optpp-q-newton # (default) optpp-q-newton | nl2sol |
19     ncsu-direct

```

```

18
19
20 ##### Method Independent Parameters #####
21 #####
22 set Maximum iterations = 200                # (default) 100
23 set Maximum function evaluations = 2000      # (default) 1000
24 set Constraint tolerance = 1.0e-4           # (default) 1.0e-4
25 set Convergence tolerance = 1.0e-4          # (default) 1.0e-4
26
27 ##### Numerical Gradient Parameter #####
28 #####
29 set Numerical gradients = true               # (default) false | true
30 set Numerical gradient type = central        # (default) forward | central
31
32
33 ##### Method Specific Parameters #####
34 ##### OPT++ #####
35 #####
36 subsection OPT++
37     set Gradient tolerance = 1.0e-4          # (default) 1.0e-4
38     set Steplength to boundary = 0.2          # (default) 0.9
39     set Centering parameter = 0.8            # (default) 0.2
40     set Merit function = argaez_tapia         # (default) argaez_tapia
41 end
42 end
43
44 subsection Design Variables
45 set num_design_variables = 1
46 set DV_0.name = L_CCL
47 set DV_1.name = prc_N_c
48
49 ##### Initial Point #####
50 #####
51 set DV_0.ip = 1.65e-4
52 set DV_1.ip = 0.30
53
54 ##### Lower Bound #####
55 ##### lb < -1e30 for -inf #####
56 #####
57 set DV_0.lb = 0.8e-4
58 set DV_1.lb = 0.20
59
60 ##### Upper Bound #####
61 ##### ub > 1e30 for inf #####
62 #####
63 set DV_0.ub = 10e-4
64 set DV_1.ub = 0.50
65
66 ##### Scales #####
67 #####
68 set DV_0.scale_method = value                # none | auto | value | log
69 set DV_1.scale_method = value                # none | auto | value | log
70
71 set DV_0.scale = 1e-4
72 set DV_1.scale = 0.1
73
74 ##### Step size #####
75 #####
76 set DV_0.step = 1e-5
77 set DV_1.step = 1e-4
78
79 end
80
81 subsection Responses
82     set num-objectives = 1

```

```

83  set num_nl_constraints = 3
84  set num_eq_constraints = 0
85
86  set RESP_0_name = current
87  set RESP_1_name = m_Pt_c
88  set RESP_2_name = epsilon_V_cat_c
89  set RESP_3_name = epsilon_N_cat_c
90  set RESP_4_name = epsilon_S_cat_c
91  set RESP_5_name = L_CCL
92
93  ##### Response Numbers must match #####
94  ##### Constraint Lower Bound #####
95  ##### lb < -1e30 for -inf #####
96  #####
97  set RESP_2_lb = 0.118
98  set RESP_3_lb = 0.118
99  set RESP_4_lb = 0.118
100 set RESP_5_lb = 0.8e-4          # (ESDLab, Ultra-thin CCM, = 2 microns) 2e-4
101
102  ##### Constraint Upper Bound #####
103  ##### ub > 1e30 for inf #####
104  #####
105  set RESP_2_ub = 1.0
106  set RESP_3_ub = 1.0
107  set RESP_4_ub = 1.0
108  set RESP_5_ub = 2e-4          # (ESDLab, Ultra-thin CCM, = 2 microns) 2e-4
109
110  ##### Equality Constraint #####
111  #####
112  set RESP_1_eq = 350
113  end
114 end

```

In the above example of a `opt_app_optimization` file we will note that many of the variables have been seen earlier in the `opt_app_parametric` file. These next sections will look at describing the additional changes and variables applicable to optimization in FCST.

Optimization Method: The `Optimization method` command is used to specify the type of study that is being carried out. There area

1. `single_method`

The `single_method` is selected when the user is running parametric studies or optimization where they require only one optimization method.

2. `multi_start`

The `multi_start` method will restart the optimization multiple times specified by the user.

3. `pareto_set`

The `pareto_set` method is only utilize during multi-objective optimization (4.4).

4. `hybrid`

The `hybrid` method uses additional optimization methods. An example of this would be to use a global method to locate an area in the entire feasible region. Then once a sufficient criteria has been met the optimization method will be changed to a local method in order to take advantages of the high convergence rate.

Optimization Program Options: The Optimization Program Options consist of the same variables as seen in `opt_app_parametric` file however we also notice three additional Classifications:

1. Method Independent Parameters
2. Numerical Gradient Parameters
3. Method Specific Parameters

Method Independent Parameters: Consists of parameters that have no dependencies on the type of optimization method being used. This section tells FCST the maximum number of iterations & function evaluates (*line 22 & 23*) that can be carried out during optimization.

It also sets how strictly the method sticks to the constraints and the tolerance needed for convergence (*line 24 & 25*).

Note: Depending on the optimization problem, sometimes convergence issues can arise. One way to alleviate this issue is to relax the **Convergence tolerance** from the default $1.0e^{-4}$ to maybe $1.0e^{-3}$.

The same idea can be applied to the **Constraint tolerance** depending on how heavily constrained the problem is.

Numerical Gradient Parameters: Here is where we specify the type of gradient method we want to employ.

1. Numerical Gradients, as seen in the example (*line 30*)
2. Analytical Gradients

When using numerical gradients we also have an additional specification on whether we want to use *Forward* or *Central* differentiation (*line 31*).

As we can see from figure 4.8 using central differentiation is a much more accurate form of predicting the slope of a function. Having said this we must also take note of equations 4.1 & 4.2. In equation 4.2 we can see that we have doubled the function evaluations which in turn doubles the amount of time required to carry out the analysis.

In some cases when carrying out function evaluations they will be highly expensive or in some cases convergence can be an issue. In these cases although not ideal it is preferable to use *Forward* differentiation

1. Forward

$$\frac{\Delta f}{\Delta x} = \frac{f(x + \Delta x) - f(x)}{\Delta x} \quad (4.1)$$

2. Central

$$\frac{\Delta f}{\Delta x} = \frac{f(x + \frac{\Delta x}{2}) - f(x - \frac{\Delta x}{2})}{\Delta x} \quad (4.2)$$

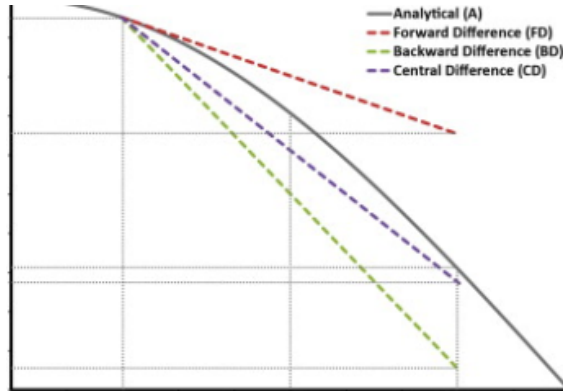


Figure 4.8: Comparison of Forward, Backward, & Central Differentiation

Method Specific Parameters: This section is specific to the method being used. In the above example it is specific to the *OPT++* library. An additional example has been given below however if curious the reader is advised to see the default optimization methods located in:

```
1 $./data/cathode/optimization/optimization_methods_cathode/
```

or

```
1 $./data/mea/optimisation/optimization_methods_mea/
```

In the following short example we are using a method from the SCOLIB library, the `coliny_pattern_search` algorithm. In this case we would change the `Optimization method = coliny_pattern_search` as appose to `optpp-q-newton` (line 17).

We then would then replace (line 33 - 41) in the above `opt_app-optimization` file with the new method specific section.

```
1 ##### Method Specific Parameters #####
2 ##### SCOLIB (COLINY) #####
3 #####
4 subsection coliny_pattern_search
5     set Initial Delta = 2           # (default) 1
6     set Threshold Delta = 0.0001   # (default) 0.0001
7 end
```

Design Variables Section: The `Design Variables` Section is similar to the `opt_app-parametric` file except for two additional subsections.

1. Scales
2. Step size

Scales: The scales section has two specifications

1. `scale_method`

The `scale_method` specifies whether you are going to specify no scale (`none`), auto scaling, `log`, or a `value`. In general it is good practice to specify a scale `value` as it allows the user to have a definite reference point, when using `auto` if there is a change in magnitude it will go unnoticed by the user in the final output solution.

2. scale value

The scale value is the magnitude of the variable. For example if the variable is temperature we know that the scale is 100 as temperature is given in Kelvin (353 - 368 [K]). If its Nafion loading the scale is 0.1 as Nafion loading is a percentage (20 - 50 %).

Step Size: The step size refers to the Δx in equations 4.1 & 4.2. Greater the step size the less computations that will be required, however this also means the greatest error as the error is proportional to $(\Delta x)^2$. Therefore there is a fine trade off between computational time and error.

Responses Section: The Responses section has changes slightly compared to the `opt_app_parametric` file as we are now considering constrained optimization. If the above example was unconstrained optimization there would be no difference between the `opt_app_parametric` and `opt_app_optimization` responses section.

There are two types of constraints:

1. Linear (Equality) Constraints (*line 83*)
2. Non-Linear Constraints (*line 84*)

In the above case we have three non-linear constraints and one linear constraint.

Non-Linear Constraints: Like the **Design Variable** section each nonlinear constraint requires a upper and lower bound (*line 97 - 108*). If no finite upper or lower bound is to be specified $1e^{30}$ or $1e^{-30}$ can be specified.

Linear (Equality) Constraints: Unlike Non-Linear Constraints, Equality constraints only require the response variable to equal a value (*line 112*).

4.4 Multi-Objective Optimization using FCST

To achieve multi-objective optimization we must first change three parameters.

1. `Optimization strategy` (*line 16*)
2. `num.design.variables` (*line 84*)
3. `num.objectives` (*line 82*)

Optimization strategy When carrying out multi-objective optimization we can no longer optimize for just one objective function this is especially the case when an improvement of one objective comes at the expense of another (*Performance & Cost*). In order account for the additional objective function we incorporate weighting factors which specifies the importance of one objective over the other. The weights are referred to a **Pareto Weights** or **Pareto Set**.

In FCST the default Pareto set is for two design variables. Figure 4.9 below shows the multi-objective weights for two design variables.

Pareto Set #	Obj_Function_1	Obj_Function_2
0	1.0	0.0
1	0.9	0.1
2	0.8	0.2
3	0.7	0.3
4	0.6	0.4
5	0.5	0.5
6	0.4	0.6
7	0.3	0.7
8	0.2	0.8
9	0.1	0.9
10	0.0	1.0

Figure 4.9: Pareto Set for 2 Design Variables

num_design_variables & num_objectives: Once the `Optimization` strategy has been set to `pareto_set` we then change both the `num_design_variables` & `num_objectives` to 2 or whatever number of design variables are specified. At present FCST like most multi-objective engineering problems, considers only two design variables however this can be easily modified by changing the default Pareto set found in `dakota_application.cc`.

4.5 DAKOTA Methods

The following list is all of the current DAKOTA Methods available as of **1-MAY-2013**. The methods are known to work with FCST and can be utilized. For detailed descriptions on the individual methods see DAKOTA manuals.

- | | | |
|--|---------------------------------------|---|
| 1. asynch_pattern_search | 19. efficient_global | 37. <code>npsol_sqp</code> |
| 2. <code>bayes_calibration</code> | 20. <code>fsu_cvt</code> | 38. <code>optpp_cg</code> |
| 3. <code>centered_parameter_study</code> | 21. <code>fsu_quasi_mc</code> | 39. optpp_fd_newton |
| 4. coliny_cobyla | 22. <code>global_evidence</code> | 40. optpp_g_newton |
| 5. coliny_direct | 23. <code>global_interval_est</code> | 41. <code>optpp_newton</code> |
| 6. coliny_ea | 24. <code>global_reliability</code> | 42. optpp_pds |
| 7. coliny_pattern_search | 25. <code>importance_sampling</code> | 43. optpp_q_newton |
| 8. coliny_solis_wets | 26. <code>list_parameter_study</code> | 44. <code>polynomial_chaos</code> |
| 9. conmin_frcg | 27. <code>local_evidence</code> | 45. psuade_moat |
| 10. conmin_mfd | 28. <code>local_interval_est</code> | 46. <code>richardson_extrap</code> |
| 11. <code>dace</code> | 29. <code>local_reliability</code> | 47. <code>sampling</code> |
| 12. <code>dl_solver</code> | 30. moga | 48. soga |
| 13. <code>dot</code> | 31. multidim_parameter_study | 49. <code>stanford</code> |
| 14. <code>dot_bfgs</code> | 32. ncsu_direct | 50. <code>stoch_collocation</code> |
| 15. <code>dot_frcg</code> | 33. nl2sol | 51. <code>surrogate_based_global</code> |
| 16. <code>dot_mmfd</code> | 34. <code>nlpql_sqp</code> | 52. <code>surrogate_based_local</code> |
| 17. <code>dot_slp</code> | 35. <code>nlssol_sqp</code> | 53. <code>vector_parameter_study</code> |
| 18. <code>dot_sqp</code> | 36. <code>nonlinear_cg</code> | |

4.6 Fuel Cell Design & Optimization Using FCST

As we've seen above FCST also has the capabilities to perform optimization studies. Any application that is inherited from `OptimizationBlockMatrixApplication` has the appropriate interface to be used for optimization studies. Information on how to run optimization can be found in sections 4.3 & 4.4.

To perform optimization studies, FCST interfaces with the open source libraries DAKOTA developed by Sandia National Laboratory. For more information about the DAKOTA library please [click here](#). The FCST developers have developed an interface so that DAKOTA and FCST can interact seamlessly.

4.6.1 FCST classes that interact with DAKOTA (Developers Only)

Interaction between FCST and DAKOTA is achieved by using `simulation_builder` which will call the `run_optimization()` function.

When FCST is run as seen in figure 4.3 the FCST code is called on once in order to run a specific data point. However in parametric or optimization studies we require multiple points to be evaluated. This requires the use of the DAKOTA libraries in order to change the variables after each iteration. The two main files used to interface with DAKOTA are:

1. `dakota_direct_interface`
2. `dakota_application`

Once the initial stages of the code have been carried out by `simulator_builder`, `simulator_selector`, and `dakota_application`, declaring and initialing all the variables from the `main_app_`, `data_app_`, & `opt_app_` files. The `main.cc` file then proceeds to the `run()` function in `simulator_builder.cc` (see below) in order to run the simulation.

In the `run()` function we can see in line 10 where the code checks to see if its running an analysis or parametric/optimization study, as explained in 4.2.1. During parametric/optimization studies the code will enter line 12 and proceed to the `run_optimization()` function in `simulator_builder.cc`.

```
1 template<int dim>
2 void SimulatorBuilder<dim>::run()
3 {
4     timer.restart();
5
6     if (run_tests) run_test();
7     else
8     {
9         if (dakota_use || dakota_direct)
10        {
11            run_optimization();
12        }
13        else
14        {
15            //-- Select the application you want to run:
16            app_lin = sim_selector->select_application();
17            //-- Select the solver you want to run:
18            newton = sim_selector->select_solver(app_lin.get());
19            //-- Select the solving method you want to run, e.g. adaptive refinement:
20            solver = sim_selector->select_solver_method(app_lin.get(), newton.get());
21            // Here we have collected all information:
22            deallog << "Run program using input file: " << simulator_parameter_file_name << std::endl;
23            deallog.pop();
24            solver->solve(simulator_parameter_file_name, param);
25            timer.stop();
26        }
27    }
28
29    timer.stop();
```

```

30 deallog.push("MAIN");
31 deallog << "The program was executed in: " << timer.wall_time() << " seconds " << std::
    endl;
32 deallog << "===== END =====" << std::endl;
33 deallog.pop();
34
35 }

```

The main points to note once we enter the `run_optimization()` function are:

1. Is DAKOTA running in Parallel or Series? (*line 8*)
As of **1-MAY-2013** Series is the only option available. This may change in the future.
2. Are we running a Non-Linear Least Squares (NLS) method or standard parametric/optimization routine? (*line 16-25*)

Note: These are questions that are answered in the `opt_app_` file explained earlier in section 4.3.

Once these have been specified the code will execute the `run()` function (*line 28*), which begins the iterative loop until the parametric study has been complete or the stopping criteria have been met in optimization. An illustration of this can be seen in figure 4.10 taken from Peter Dobson's 2012 paper.

```

1 void SimulatorBuilder<dim>::run_optimization()
2 {
3     deallog.pop();
4     if (dakota_direct)
5     {
6         // NOTE: Must declare these in order for parameter handler to not complain when reading
6         //         the parameter file specified.
7         //         Not exclusively required for dakota application to run.
8         Dakota::ParallelLibrary parallel_lib;
9         shared_ptr<Dakota::ProblemDescDB> problem_db(new Dakota::ProblemDescDB (parallel_lib));
10        SIM::DakotaApplication optimization(problem_db, optimization_parameter_file_name);
11        optimization.declare_parameters(param);
12        optimization.manage_inputs(param);
13
14        Dakota::DirectApplicInterface* optimization_interface;
15
16        if (optimization.use_NLS())
17        {
18            deallog<<"Entering DakotaLeastSquaresInterface"<<std::endl;
19            optimization_interface = new SIM::DakotaLeastSquaresInterface<dim> (optimization,
20                problem_db, param, sim_selector, simulator_parameter_file_name);
21        }
22        else
23        {
24            deallog<<"Entering DakotaDirectInterface"<<std::endl;
25            optimization_interface = new SIM::DakotaDirectInterface<dim> (optimization,
26                problem_db, param, sim_selector, simulator_parameter_file_name);
27        }
28        optimization.assign_interface(optimization_interface);
29        optimization.run();
30
31        deallog << "Optimization completed" << std::endl;
32
33

```

If running a standard parametric/optimization routine, the following `dakota_direct_interface` function will be used.

```

1 template <int dim>
2 int DakotaDirectInterface<dim>::derived_map_ac(const Dakota::String& ac_name)

```

If running a Non-Linear Least Squares (NLS) method, the following `dakota_direct_interface` function will be used.

```

1 template <int dim>
2 int DakotaLeastSquaresInterface<dim>::derived_map_ac(const Dakota::String& ac_name)

```

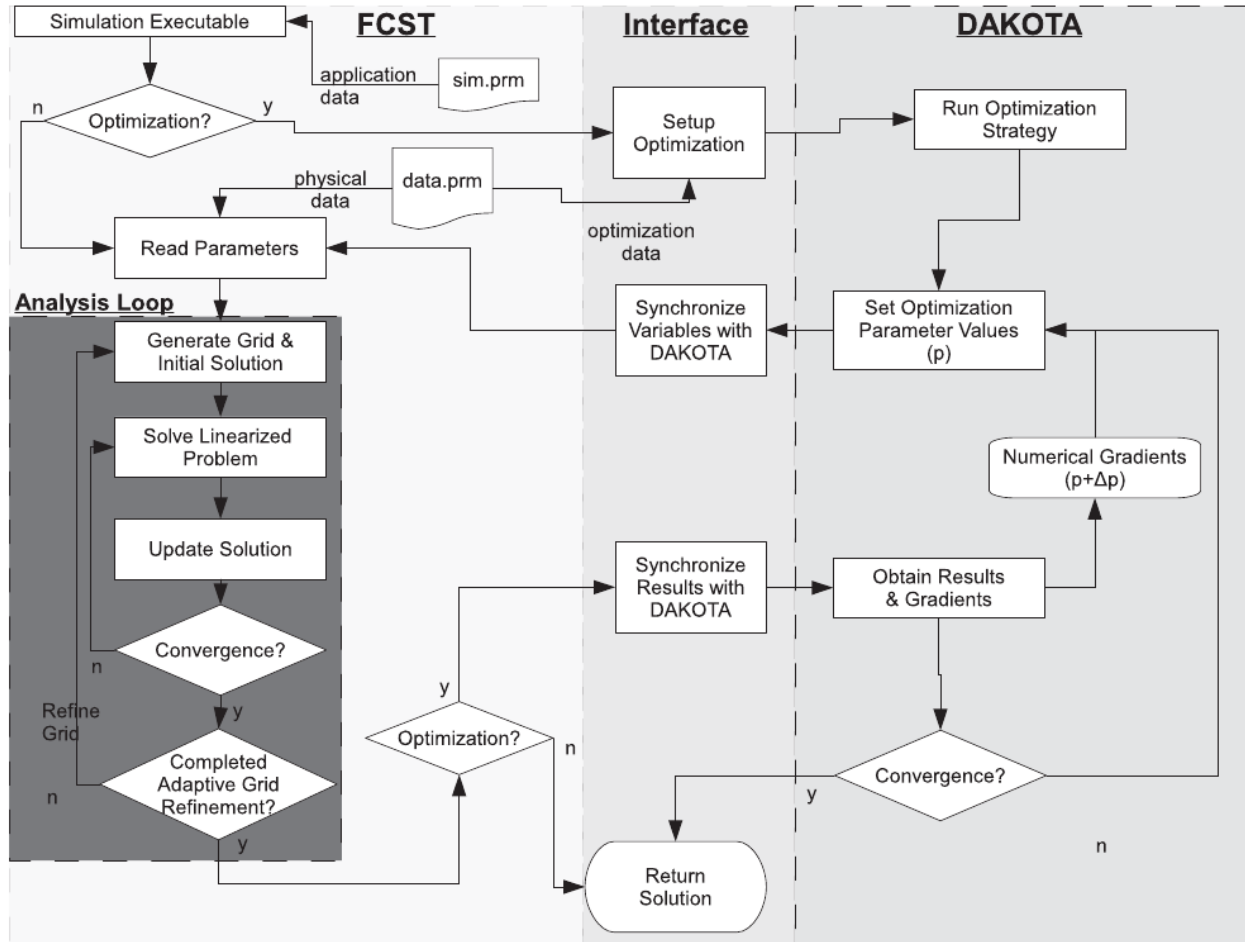


Figure 4.10: Schematic of Fuel Cell Analysis Code and DAKOTA Optimization Interface (Dobson, 2012)

Chapter 5

Post-processor

FCST can output result in many different formats using the deal.II output parser. FCST developers however output the solution in .vtk format and use the open-source post-processing software [Paraview](#) to analyze their results. ParaView is an open-source data analysis and visualization program. ParaView can run in multiple operating systems. Using Paraview users can quickly analyze their data visually using qualitative and quantitative methods already implemented in the software.

A Paraview tutorial can be found at the following [site](#). Wolfgang Bangerth and Timo Heister recently published a very good lecture on how to use Paraview at the following [site](#)

Part II

Developer's Reference Guide (Under development)

Chapter 6

Preliminaries

6.1 Setting up FCST under KDevelop

If you are going to be developing new routines for FCST, we recommend that you use KDevelop. In order to setup a KDevelop project with FCST follow the steps below:

- In the main menu, go to Setting > Configure KDevelop... Select the Background Parser tab. Disable the Background Parser. Note this is necessary because FCST is a large code and, unfortunately, parsing takes a very long time.
- Go to Projects > Open/Import Project... Select the FCST folder. In the next window, select Generic Makefile. At this point, the project will appear on the left hand side and you can browse through all files.
- Next, we will setup the environment to run and debug the code within KDevelop.
- Go to Run > Configure Launches...
- Press the '+' button on the top of the window. Once you press this button, a new option will open under either Global or FCST. Select New Native Application Configuration
- On the right of the window, under Executables, enter the FCST binary file. For example,
- Under Behaviour, in Working Directory enter the data folder from which you would like to run the code. In Arguments, enter the main parameter file, see Figure 6.1.

6.1.1 Formatting OpenFCST files

All files should start with the following information:

```
1 // -----
2 //
3 // FCST: Fuel Cell Simulation Toolbox
4 //
5 // Copyright (C) 20XX-20XX by Energy Systems Design Laboratory, University of Alberta
6 //
7 // This software is distributed under the MIT License
8 // For more information, see the README file in /doc/LICENSE
9 //
10 // - Class: class_name
11 // - Description: short description of class
12 // - Developers: name_developers, affiliation
13 // - Id: $Id$
```

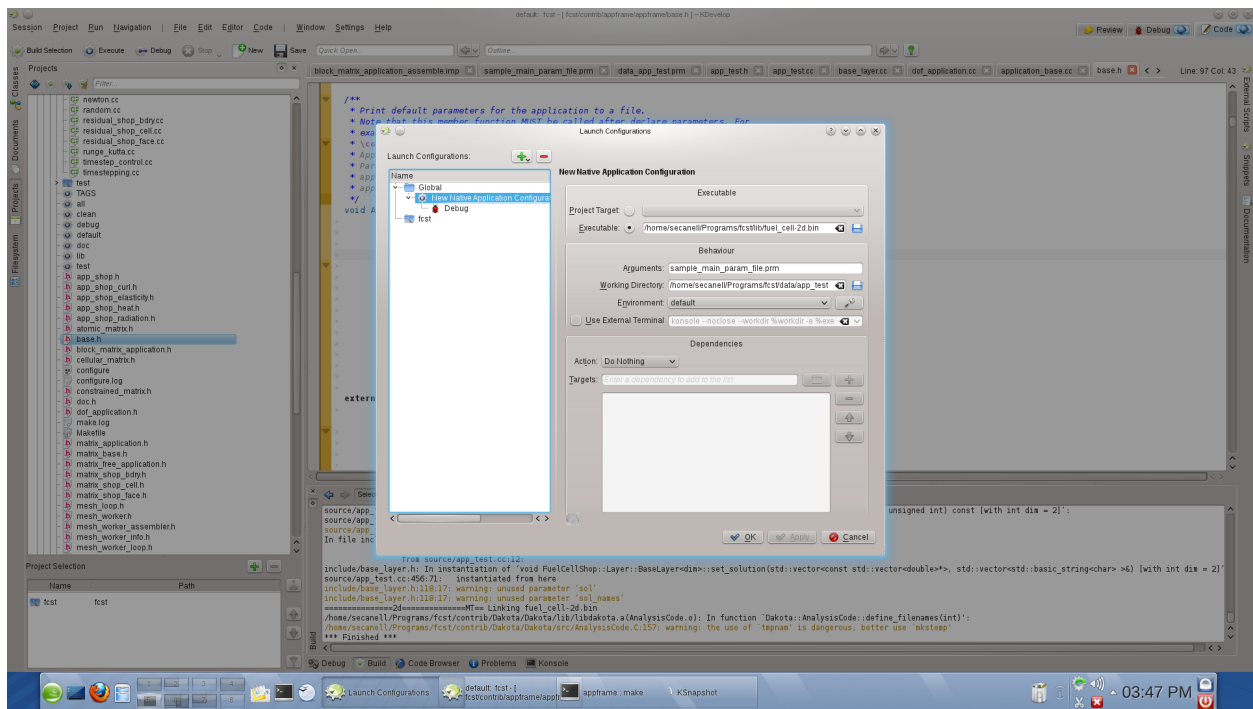


Figure 6.1: Configuring Configure Launches... in KDevelop

14 //
15 //

In order to keep the formatting of all files consistent, it is recommended to use the space style for code readability. In KDevelop, set your formatting options:

- In the main menu, go to Setting > Configure Editor.
- In the 'Editing' section, select the Indentation tab.
- Set 'Indent Using' to *Spaces*, and set the spacing to **4 characters**.

Chapter 7

FCST structure

7.1 Directory tree

FCST contains six subfolders, namely:

- FuelCell/lib Contains the binary executable fuel cell simulator once FCST has been compiled. To compile FCST enter the FuelCell folder, change the Makefile to the correct path for Deal.II and Deal.II libraries and typing `$make`.
- FuelCell/include Contains all include files (*.h)
- FuelCell/source Contains all source files (*.cc)
- FuelCell/doc Contains all documentation. This includes the Users Manual in html (the main page is `index.html`). To generate the manual, enter the folder FuelCell and type

```
1 $make doc.
```

To do so, Fuel Cell uses the free package Doxygen. In the makefile the path to Doxygen is specified by the variable `DOXYGEN_PATH`. The default location is `/opt/local/bin/doxygen`.

- FuelCell/data Contains data used to run several of the applications in FCST.
- FuelCell/test - Used for CDash (see section 12)
- FuelCell/contrib - Contains OpenSource libraries and codes that have been developed by other people and are used within FCST. This include AppFrame (developed by G. Kanschat) and DAKOTA (developed by Sandia National Labs). Note that the codes have been modified.

The main program file is `main.cc` in FuelCell/source. This file creates:

- A NewtonExecution object. This object is used to implement the mesh adaptive loop
- NewtonExecution object. This object is used to implement the mesh adaptive loop
- A linear application that implements the fuel cell equations (linearized version of them). There are several linear applications. The linear solver implements:
 - `cell_residual()`: This member function is called by `dof_application.cc` in AppFrame in order to implement the residual. `cell_residual()` is in charge to compute the residual for a given cell.
 - `cell_matrix()`: This member function is called by `block_matrix_application.cc` (via `optimization_block_matrix_application.cc`) and is used to assemble the cell matrix. `block_matrix_application.cc` uses this information to assemble the stiffness matrix for the complete problem.
 - `solve()`: This member function is used to solve the linear system.

7.2 Understanding FCST Architecture

EXPLAIN WHAT IS AN APPLICATION, PHYSICS, ETC.

7.3 Understanding FCST Applications: The FCST tutorials

FCST contains several tutorials to get you started developing your own applications. Currently two tutorial applications have been developed

- Cathode application
- Cathode and membrane application

You can find these two tutorials in the Modules section of the DOxygen documentation, i.e. in file `/doc/html/modules.html`. All FCST developers learnt to develop applications by first reading these tutorials. If you are developing new physics classes, then you will be relying heavily on classes from the [deal.II](#) finite element libraries. If this is the case, the FCST developers would recommend any new developers to look at the tutorials provided in the [deal.II](#) website.

!!!!!!!!!!!!!! IS THERE ANYWAY WE CAN INSERT THE TUTORIALS FROM DOXYGEN HERE !!!!!!!!!!!!!!!

7.4 FCST Applications

7.4.1 Data files

It is recommended that every application also contains a data file in `/fcst/trunk/data` with a folder name corresponding to the name of the application. The data folder should contain four sub-folders as follows

- analysis: This folder contains default (and well documented) main, data and mesh input files to run a sample analysis problem.
- parametric: This folder contains default (and well documented) main, data, mesh and optimization files to run a parametric study using FCST and Dakota
- optimization: This folder contains default (and well documented) main, data, mesh and optimization files to run a parametric study using FCST and Dakota

7.5 Namespace structure

FCST contains four namespaces, namely

- *FuelCell*
- *FuelCellShop*
- *AppFrame*
- *AppFrameShop*

Namespaces *AppFrame* and *AppFrameShop* designate member function in the contributing library *AppFrame* which was originally developed by Dr. Guido Kanschat at the University of Heidelberg and is currently maintained by Dr. Guido Kanschat and the authors of Fuel Cell Simulation Toolbox (FCST).

Namespaces *FuelCell* and *FuelCellShop* form the core of FCST. Namespace *FuelCell* contains an *Application* and *InitialSolution* namespace as well as several classes such as *OperatingConditions*. Application namespace contains classes that can be used to solve a specific problem such as fluid flow in a channel, or

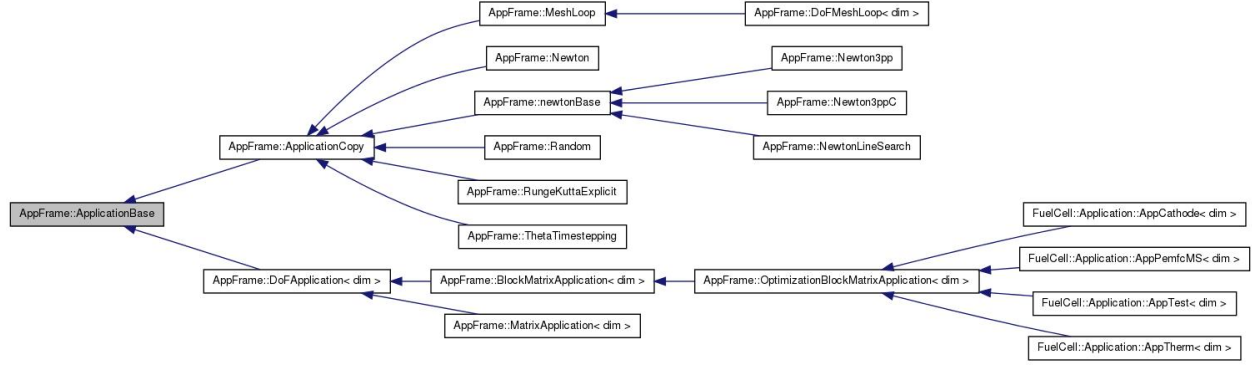


Figure 7.1: Inheritance tree for ApplicationBase

the physical processes occuring in the cathode of a fuel cell. Based on the nature of the application, two types of classes are available:

- *AppFrame::DoFApplication*
- *AppFrame::ApplicationCopy*

Figure 7.1 shows an overview of the two types of applications.

Classes inherited from *AppFrame::DoFApplication* are used when we need to implement the governing equations of the physical problem, i.e. the weak form of the partial differential equations. Class *AppFrame::DoFApplication* implements all the methods used to assemble the right hand side, i.e. it contains a Triangularization (domain mesh), a deal.ii DoFHandler and several other objects to loop over cells. Class *AppFrame::BlockMatrixApplication* is a child of *AppFrame::DoFApplication* and contains additional functionality in order to assemble and store the global system matrix into a BlockMatrix object. Finally, class *AppFrame::OptimizationBlockMatrixApplication* implements optimization functionality such as functional evaluation. FCST applications that require assemble of a system matrix and right hand side are inherited from this application such as *FuelCell::AppCathode*.

Figure 7.2 provides an example of the inheritance tree for *FuelCell::AppCathode*. AppCathode inherits all the functionality of *AppFrame::DoFApplication*, *AppFrame::BlockMatrixApplication* and *AppFrame::OptimizationBlockMatrixApplication*. The responsibility of the FCST applications in namespace *FuelCell* is to initialize all the variables and to implement three main routines

- `cell_matrix()`
- `cell_residual()`
- `solve()`

The first two routines are used to implement the element-wise system matrix and the element-wise right hand side. The latter member function is use to solve the global finite element problem. A tutorial on how to develop an application can be found in the HTML documentation.

Classes inherited from *AppFrame::ApplicationCopy* are used to implement iterative loops. For example, when solving a nonlinear problem, a linear problem is solved iteratively. Therefore, classes that inherit from *AppFrame::ApplicationCopy* usually contain an application that inherits from *AppFrame::DoFApplication*. In terms of FCST, FCST developer will usually implement *AppFrame::DoFApplication* and use the already implemented classes of type *AppFrame::ApplicationCopy* in order to develop iterative loops for adaptive refinement, nonlinear problems and time-dependent problems.

As an example, in `simulation_builder.cc` the following process is employed to solve a nonlinear problem:

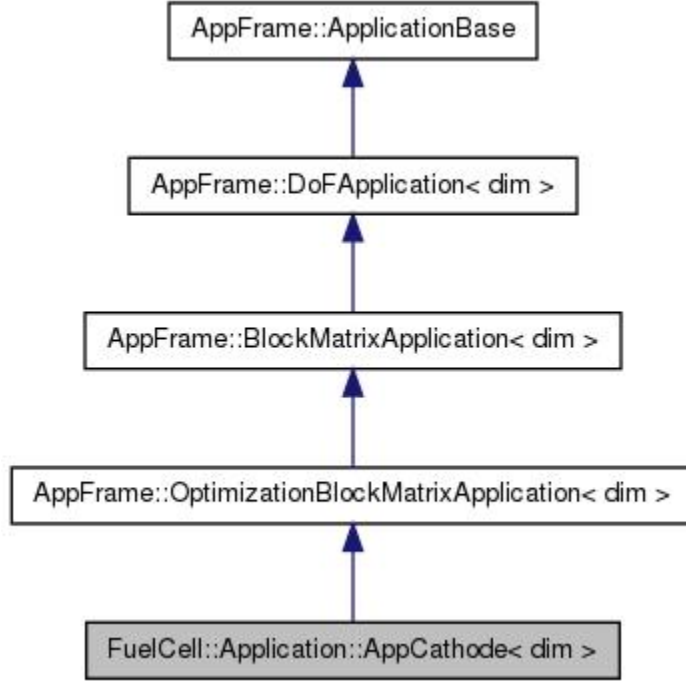


Figure 7.2: Inheritance tree for FuelCell::Application::AppCathode

```

1  //-- Select the application you want to run:
2  app_lin = sim_selector->select_application();
3  //-- Select the solver you want to run:
4  newton = sim_selector->select_solver(app_lin.get());
5  //-- Select the solving method you want to run, e.g. adaptive refinement:
6  solver = sim_selector->select_solver_method(app_lin.get(), newton.get());
7  // Here we have collected all information:
8  deallog << "Run program using input file: "
9  << simulator_parameter_file_name << std::endl;
10 deallog.pop();
11 solver->solve(simulator_parameter_file_name, param);

```

In the code above, first an FCST application that inherits from *AppFrame::DoFApplication* is created. Then, the application that is used to solve the linear system of governing equations at each iteration is handed in to a Newton solver that inherits from *AppFrame::ApplicationCopy*. This solver is in turn handed to another solver that inherits from *AppFrame::ApplicationCopy* and that implements an adaptive refinement loop.

Namespace *FuelCell* is therefore a place holder for applications of type *AppFrame::DoFApplication*. This applications are the core of FCST since they assemble the system of equations that need to be solved. Users can develop their own applications by inheriting *AppFrame::OptimizationBlockMatrixApplication* and re-implementing *declare_parameters()*, *initialize()*, *cell_residual()*, *cell_matrix()* and *solve()* as shown in Figure 7.2 and explained in detail in the tutorial program for AppCathode. If the problem requires solving the problem iteratively such as in nonlinear and transient problems, the application will be handed over to an application of type *AppFrame::ApplicationCopy* to be solved iteratively.

The namespace *FuelCellShop* is divided into several other namespaces as follows

1. Material namespace: Specify the properties of common materials used in fuel cells. Examples of material classes include *PureGas* baseclass.
2. Layer namespace: Specify the different MEA components in a fuel cell. A *BaseLayer* has been developed

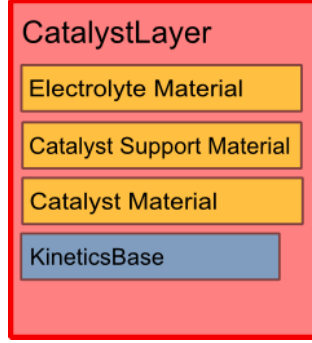


Figure 7.3: Layer namespace structure

in order to standardize this classes. They contain $material_i d$ and $bondary_i d$ elements to be able to relate the layer to the mesh as well as many other properties. Layer classes contain material classes in them that are used in order to obtain the appropriate physical parameters of the layer. Some layers are homogeneous and some are heterogeneous and anisotropic.

3. Matrix namespace (OLD): Used to assemble the governing equations of a system. For linear problems this class implements the stiffness matrix for a given equation. For nonlinear problems it generally includes $\frac{\partial R}{\partial \vec{u}}$. This matrix is used to calculate the step size in a Newton solver.
4. Residual namespace (OLD): Used to assemble the governing equations of the system. For linear system these classes contain the right hand side of the problem. For nonlinear systems they contain the residual at the previous iteration, i.e. $R(\vec{u})$.

7.6 Layers Namespace

A Layer in OpenFCST is used to define the properties of a cell in a finite element mesh. A Layer can be formed with with a single material or, in the case of composite layers such as a gas diffusion layer or a catalyst layer, it contains several materials and reaction parameters which are then used to compute the effective properties. An example of a catalyst layer is shown in Figure ??.

The FuelCellShop::Layers namespace contains all the layers available with OpenFCST. All layers inherit from BaseLayer as shown in Figure ?. BaseLayer is a virtual class. An object of this class should never be created. BaseLayer simply provides common member functions and data members that apply to all layers.

The layer classes contain a member function named `set_solution()` which parses the uni

7.7 Materials Namespace

No materials contain a set solution. Materials will only set specific variables using a routine such as `set_temperature(double)`.

7.8 Contributing libraries

FCST is distributed with copies of deal.II, Appframe, Dakota, COLDAE, ALGLIB and cpptest. These projects reside in the subdirectory `contrib/`. Please note that these projects are copyrighted by others than the FCST authors and are covered by different licenses. For details, consult their respective webpages. A copy of their respective license is provided with the code. Inside each contributing library folder you will also find a file called `README.txt`. This file contains a list of any modifications that the FCST developers have

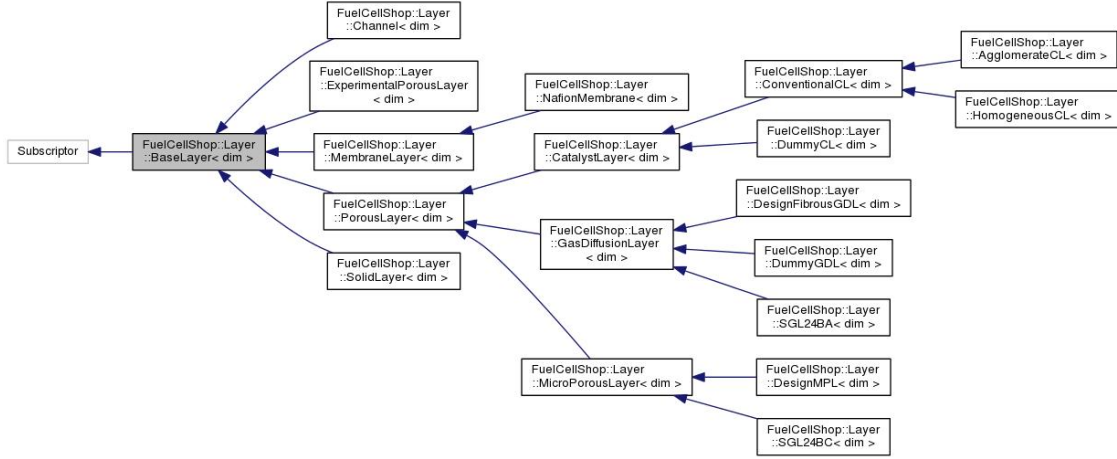


Figure 7.4: Layer namespace structure

made to the contributing libraries. Note that some FCST authors also contribute to the additional libraries. For example, Valentin Zingan is also contributor of the deal.II libraries.

7.8.1 APPFRAME

AppFrame was originally developed by Dr. Guido Kanschat at Texas A & M and it is not continued to be developed by the ESDLab group. AppFrame is a framework to develop a chain of applications. The idea of these application classes is the possibility to build a chain out of these in order to have several predefined nested solvers. For this, we distinguish applications roughly in two classes, both derived from ApplicationBase:

- Terminal applications, which implement the real finite element code like computing residuals on mesh cells, assembling matrices and solving linear systems.
- Non-terminal applications derived from ApplicationCopy; these usually implement a new solve() function as an iterative solver around another application. They implement all functions of the ApplicationBase interface, either forwarding them to the next inner application by ApplicationCopy or by providing their own implementation.

Usually a class in a chain communicates values with its next outer class through function arguments. Nevertheless, at least the terminal application will require values from even outer applications in the chain in order to compute residuals and matrices correctly. For these, the mechanism of named data provided by ApplicationData was introduced. Each class can store auxiliary data under a unique name there for use in inner iterations.

Class DoFApplication

This class is the parent of all terminal applications. It is the base class for applications requiring a Triangulation and a handler for degrees of freedom.

The mesh as well as the dof handler may be created by this class, which is the default, or they may be provided by another object, in which case they must be specified in the constructor.

Note that in this class the received or created dof handler is associated to the finite element given by the argument "Element" on the parameter file. Therefore, this class is not responsible to generate the system of equations to be solved, only to initialize the dof handler "Element" can either be a single element

of a FESystem. In the latter case, the nomenclature used in the paramter file is: set Element = FESystem[element1_type(element1_degree)^number_of_elements1-...-elementN_type(elementN_degree)^number_of_elementsN]
Example: set Element = FESystem[FE_DGQ(0)-FE_Q(1)^2]

Class BlockMatrixApplication

Text needed here

7.8.2 COLDAE Interface

The class `DAESolver`, declared in `DAE_solver.h` and defined in `DAE_solver.cc`, provides an interface to the Fortran 77 boundary-value differential algebraic equations (DAEs) code `COLDAE`. The code solves DAEs the consists of a system of mixed-order ODEs

$$u_i^{(m_i)} = f_i(x; z(u(x)), y(x)), \quad i = 1, \dots, c,$$

and algebraic constraints

$$0 = f_i(x; z(u(x)), y(x)), \quad i = c + 1, \dots, c + d,$$

for $a < x < b$. The DAE is subject to a system of mixed-point boundary conditions

$$g_j(\zeta_j; z(u(\zeta_j))) = 0, \quad j = 1, \dots, m^*,$$

where

$$a \leq \zeta_1 \leq \zeta_2 \leq \dots \leq \zeta_{m^*} \leq b,$$

and

$$m^* = \sum_{i=1}^c m_i.$$

The code `COLDAE` returns an exact solution

$$z(u(x)) = (u_1^{(1)}(x), u_1^{(m_1-1)}(x), \dots, u_c^{(m_c-1)}(x),$$

where $u_i^{(m_i)}$ is the i th derivative of u_i .

The `COLDAE` interface is demonstrated by solving the DAEs

$$\begin{aligned} z''(x) &= y(x) + \sin\left(\frac{1}{1+x}\right) + \frac{2}{(1+x)^3}, \quad 0 < x < 1, \\ 0 &= y(x) + \sin(z(x)), \end{aligned}$$

subject to the boundary conditions

$$\begin{aligned} z(0) &= 1, \\ z(1) &= \frac{1}{2}. \end{aligned}$$

The DAE along with the boundary conditions are defined by a series of functions.

Beginning with the DAE:

```
1 void fsub(double &x, double z[], double y[], double f[])
2 {
3   f[0] = y[0] + sin(1.0/(1.0+x)) + 2.0/pow(1.0+x,3);
4   f[1] = y[0] + sin(z[0]);
5 }
```

In the above function, the functions `pow` and `sin` are declared in `math.h`. The Jacobian matrix of the DAE must also be defined:

```

1 void dfsub(double &x, double z[], double y[], double df[])
2 {
3     // Declare an array of pointers for the two dimensional array
4     // that will hold the Jacobian matrix .
5     double** dfc;
6     dfc = new double*[2];
7     for (int i=0; i < 2; ++i)
8     {
9         dfc[i] = new double[3];
10    }
11
12
13    // Define the Jacobian matrix.
14    dfc[0][0] = 0.0;
15    dfc[0][1] = 0.0;
16    dfc[0][2] = 1.0;
17    dfc[1][0] = cos(z[0]);
18    dfc[1][1] = 0.0;
19    dfc[1][2] = 1.0;
20
21    // Convert the matrix dfc to a one dimensional
22    // array that Fortran will understand.
23    AppFrame::c_to_for_matrix(2,3,dfc,df);
24 }

```

In the function `dfsub`, the function `AppFrame::c_to_for_matrix` converts the C/C++ two-dimensional array `dfc` to a one-dimensional array `df`. The array `df` is then sent to **Fortran** and read as a two-dimensional array. Similar to the other math functions, `cos` is declared in `math.h`.

The boundary conditions can be defined as:

```

1 void gsub (int &i, double z[], double &g)
2 {
3     if (i == 1) g = z[0] - 1.0;
4     else if (i == 2) g = z[0] - 1.0/2.0;
5 }

```

In the above function, `i` refers to the location, between $0 \leq x \leq 1$, of the i th boundary condition. In this case, `i==1` refers to $x = 0$ and `i==2` refers to $x = 1$. Similar to `fsub`, the partial derivatives must be defined for `gsub` in a separate function.

```

1 void dgsub (int &i, double z[], double dg[])
2 {
3     if (i==1 || i == 2 )
4     {
5         dg[0] = 1.0;
6         dg[1] = 0.0;
7     }
8
9 }

```

Once the functions are defined, a few variables must be defined that contains additional information about the boundary-value DAE.

```

1 //Declare an array that holds the
2 // order of each of the ODEs.
3 int *mm = new int[1];
4 mm[0] = 2;
5
6 //Declare the location of each boundary point.
7 double *zeta = new double[2];
8 zeta[0] = 0.0;
9 zeta[1] = 1.0;

```

An instance of `DAESolver` can now be created by calling the constructor.

```

1 //Create an instance of the DAE solver class.
2 AppFrame::DAESolver *prob = new AppFrame::DAESolver
3 (1, //Number of ODES
4 1, // Number of algebraic constraints
5 mm, // Array that holds the order of each of the ODEs
6 0.0, // Leftmost boundary point
7 1.0, // Rightmost boundary point
8 zeta, // Location of boundary points
9 fsub, // ptr to ODE function
10 dfsub, //ptr to Jacobian of ODE function
11 gsub, //ptr to boundary-condition function
12 dgsub, //ptr to derivatives of boundary-condition function
13 );

```

Optional COLDAE parameters can be set by calling corresponding member function of the `DAESolver` class. For example, the number of points in the initial mesh can be set.

```

1 prob->set_initial_mesh_size(20);

```

These methods must be called before the boundary-value DAE is solved. See the `Doxygen` documentation for `DAESolver` for a complete list of methods.

Once all desired COLDAE parameters are set, the boundary-value DAE can be solved.

```

1 int flag = prob->DAE_solve();

```

The variable `flag` contains an integer value that reports the success of COLDAE; see `Doxygen` documentation. If COLDAE is successful, a continuous solution can be accessed by the use of the `DAE_solution` method. For example, suppose a solution is required for $x = 0.5$:

```

1 double x = 0.5;
2 double z[2];
3 double y[1];
4 prob->DAE_solution(x,z,y);

```

In the above code, `z` contains the solution for the ODEs and `y` contains the solution for the algebraic constraints.

7.8.3 Adding a new version of a contribution library to the repository

In order to be in the save side, follow these steps: Step 1 - Rename current `contrib_folder` folder to `contrib_folder.old`. For example, if you are trying to update `deal.II`, type the following commands on the terminal:

```

1 $svn mv deal.II deal.II.old
2 $svn commit -m"Deal directory for 7.0 moved to deal.II.old"

```

Step 2 - Download new version of `contrib_folder` from net

Step 3 - Make sure the new code and FCST compile and work fine together

Step 4 - Update subversion to now hold the "new" version of `contrib_folder`

```

1 $svn mv deal.II deal.II.old
2 $svn commit -m"Deal directory for 7.0 moved to deal.II.old"

```

Step 5 - Delete `contrib_folder.old` directory tree

Chapter 8

Coding Guidelines (DRAFT)

The purpose of this chapter is to specify coding guidelines for developers of the FCST in order to improve code understanding, reliability and readability.

It is intended that this document will collaboratively cover topics of naming, syntax, documentation, and development.

8.1 Class and Member Naming Conventions

Naming conventions are defined in this section. Consistent naming is important as it improves code understanding and readability. Distinct naming styles help us understand whether a name pertains to a type, function or variable. It is important that all names communicate without ambiguity the meaning and/or purpose of the object they represent.

Class naming:

Class names and Types should be written in camel-case with their first letter capitalized. Class names should consist of un-abbreviated nouns.

```
1 class ClassName; //Good
2
3 class my_class; //Not good
```

Function naming definition:

Function names should be written in camel-case with their first letter in lower case. Function names should contain verbs that describe their actions without ambiguity. If a class contains two functions with similar names but different purposes then at least one of the functions should be renamed.

Should we use this name convention or the following `get_potatoes()` which is what we have been using thus far. If we use `getPotatoes` we need to recode every single class... Examples:

```
1 generateInverse(double numToInvers): //Good
2
3 compute_I(double a); //Not good
```

Variable naming definition:

Use of simple variable names like `i` or `count` should be avoided for all cases except for loop counters. The variable name should reflect the content stored in the variable.

```
1 ... anodeKinetics //Good
2
3 int num //Not Good
```

Constant naming definition: Constants should be written as capital letters and the name should reflect the meaning of the constant. Also, avoid using a single letter, e.g. write `GAS_CONSTANT` instead of `R`.

```
1 SPEED_OF_LIGHT //Good
```

FCST contains a file with many constants already available named `fcst_constants.h`.

A Word on Commenting Comments can be useful tips that will help us to understand code, but should not be used primarily to help us understand complicated code. Well written code with correct object and function naming should be self explanatory without the need for excess comments.

8.2 Class and Member Document Strings

Document strings (doc strings) are comments which accompany class, function and variable definitions in the header files. They provide information to aid developers wishing to understand and utilize other's code. Documentation packages such as Doxygen can parse doc strings to produced styled, easily readable documentation with minimal developer effort. The following are doc string templates that should be implemented by FCST developers when creating new classes, functions or variables.

Class Doc String:

```
1 /**
2  *Authors    : List of name authors
3  *
4  *Description : A brief description of the classes purpose
5  *
6  *Use cases   : A list of intended uses of the class\
7  *
8  *Notes      : Other important information
9  *
10 */
```

Function Doc String:

```
1 /**
2  *Description : A brief description of the purpose
3  *
4  *Use cases   : A list of intended uses
5  *
6  *Access rules: Public/Private/Protect
7  *
8  *Inputs      : Variable descriptions and Types
9  *
10 *Outputs     : Description of output
11 *
12 *Notes      : Other important information
13 *
14 */
```

Variable Doc String:

```
1 /**
2  *Description : A brief description of the purpose, , units (if applicable)
3  *
4  *Use cases   : A list of intended uses
5  *
6  *Access rules: Public/Private/Protect
7  *
8  *Notes      : Other important information
9  *
10 */
```

Please note that the correct input syntax for Doxygen:

```
1 /**
2  *
3  */
```

8.3 Assertions and exception handling

OpenFCST includes many assertions in order to check if member function are receiving the expected data. Please make sure that all your member functions check that the data you are expect is received by the class. OpenFCST uses two types of assertions

- Assert: Checks that the desired information is provided. This assertion will only work in debug mode. This means that when running on optimized mode this check will not take place. However, this also means that the code performance will not be impacted once you run in optimized mode, i.e. the default compilation method. If you are coding, always work on debug mode. If you are developing routines, always work on optimized mode.
- AssertThrow: Some assertions check that the parameters in the input file are correct. Such assertions should be active in either debug or optimized mode. For such cases use AssertThrow.

An example of an Assert call is as follows:

```
1  Assert( solution_vector.size() == residual_vector.size() ,  
2      ExcMessage( "Solution and residual vectors are not the same size in Class XX,  
                  Function YY" ) );
```

In this case, if solution and residual are the same size, the code will continue without any problems. if solution and residual are of different size, i.e. if the assertion is FALSE, then it will output the ExcMessage.

Chapter 9

Developing Documentation in FCST

FCST documentation consists of two documents, the User and Developer's Reference Guide that you are currently reading (located in `/fcst/doc/RefGuide/`) and the HTML class documentation (located in `/fcst/doc/html/`). In order to have access to the latter, the documentation needs to be compiled using DOxygen by issuing the command `make doc` in a LINUX terminal. In the following section, the guidelines for developing the two documents are discussed.

9.1 Developing the User and Developer's Reference Guide

9.2 Developing DOxygen documentation

THIS SECTION STILL NEEDS TO BE DEVELOPED

9.2.1 TODO list in HTML documentation

If you would like to include new tasks to the TODO list, you can include them in the `*.h` file where the task needs to be done. DOxygen will move all TODO tasks to a page in the HTML documentation. The DOxygen documentation has been setup by Peter Dobson to contain three TODO subcategories in order of priority. To include a TODO task, go to the `*.h` file and type the following:

```
1 \todo1 Task to do — Top priority
2 \todo2 Task to do — Medium priority
3 \todo3 Task to do — Low priority
```

9.2.2 Linking to other functions

While referencing to a particular method used while explaining a function, it can be linked to the application by using `#` before the method name. If the method belongs to the same class, then this would suffice. Else, we can use the full namespace definition of the function in the documentation. Doxygen will automatically link the function to its documentation. Same thing can be done for the data members.

For example:

```
1 /** This structure has two constructors. Default constructor doesn't set any value. It also
    sets the
2  *   boolean member #initialized to \p \b false. This can be checked by using #
    is_initialized member function and(...)
3  */
```


Chapter 10

Development Process

This section outlines first the approach that developers should take when approaching a new project, i.e. modify the code directly or create a new branch of the code using Subversion that we can then merge into the main trunk. Next, the section outlines a development method known as Test driven development (TDD). TDD insures thorough testing of code throughout its development and implementation life cycle, resulting in improved reliability.

Coupled with the process of Refactoring, TDD produces robust code that is easily read and understood. Concepts of TDD and Refactoring shall be briefly explain in the following sections.

10.1 Proposed Development Cycle

In order to reduce the number of undesired bugs in FCST, the following development cycle should be used when modifying FCST. If you decide to modify FCST you have three options depending on the purpose of the changes:

- Modifications to **trunk** directory. If only minor changes are made to the FCST interface, i.e. you are developing new classes or applications that are not core components of FCST, changes can be performed directly in the **trunk** of FCST. Before committing any changes make sure the code compiles AND that the code passes all FCST tests by running the test script **run_tests**.
- Creation of **branches**. If you expect to modify any core classes of FCST such as a base class or AppFrame, it is recommended that the developer creates a new branch for the code, makes all desired modifications, makes sure the code compiles in several operating systems such as OpenSUSE and Fedora, makes sure the code passes all FCST tests by running the test script **run_tests** and then, merge the branch with the trunk.
- **stable_release** creation. Once a year, a new release of FCST will be developed. A **stable_release** is the version of FCST that will be available on the OpenFCST website.

10.2 Test Driven Development

Test Driven Development (TDD) is a software development methodology which is rather different compared to the typical development process generally acquired when learning programming. Imagine a programmer is given a problem for which they must provide a software solution. Instead of diving in “head first” and writing code to provide the solution, a TDD programmer first writes a number of Unit tests. Unit testing is a method by which individual units of source code are tested to determine if they are fit for use. In object oriented programming units are individual member functions. The Unit tests define acceptable behavior of the code that the programmer intends to create. Once the Unit tests have been created the programmer

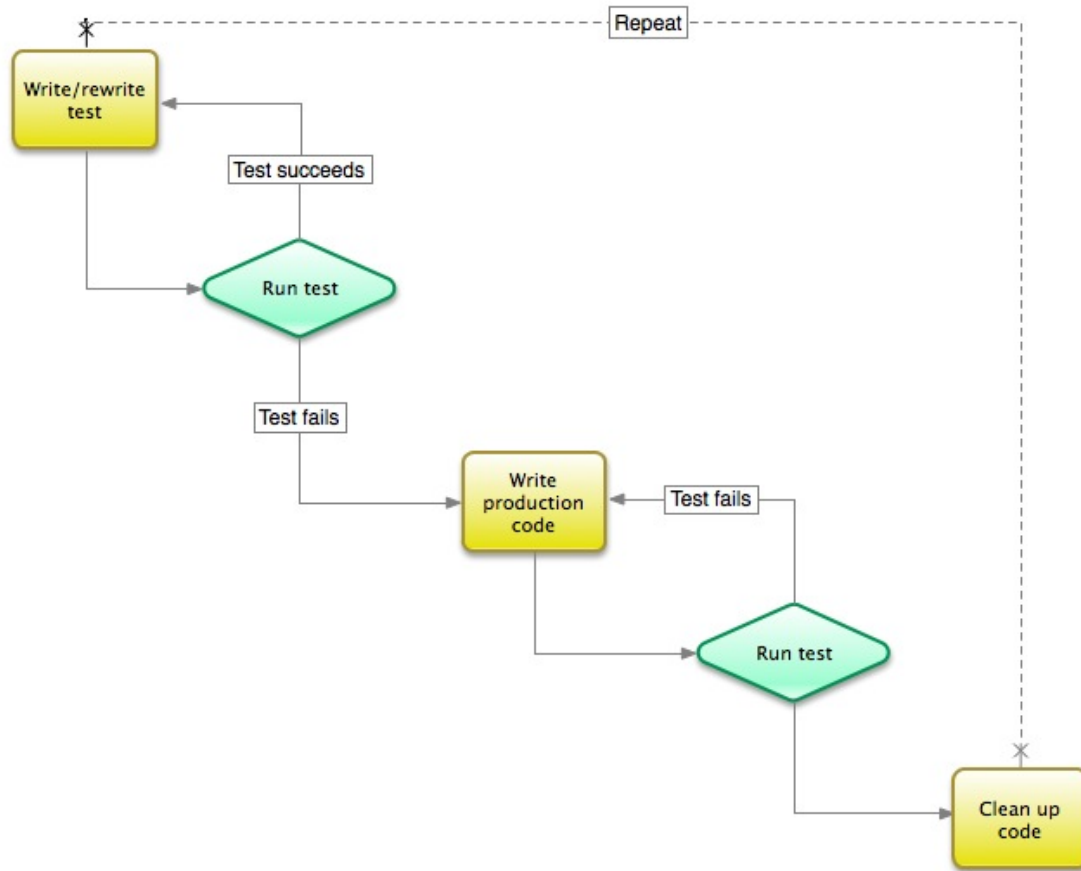


Figure 10.1: TDD Cycle

may then write the actual code that will provide their programming solution. Whilst writing this code the programmer uses their Unit tests to ensure the written code behaves correctly,i.e. passes the test.

A more detailed description of the TDD methodology as seen in figure ?? :

1. Creation of a set of Unit tests that define the correct behavior of production code. Note: We must ensure that these tests initially fail.
2. Creation of production code and subsequent checks to see if it passes unit tests. Work on production code continues until all tests are passed.
3. Code is cleaned. Refactoring increase readability and understanding of code.
4. More test cases may be added in order to ensure sufficient testing. The number of unit tests required for satisfactory testing is subject to the programmers judgment.

Advantages of TDD are as follows:

1. Increased reliability of code
2. Programmers who write more tests are more productive

3. Not just a validation of correctness: TDD also drives development by forcing the programmer to think strongly about how their code will be used. This leads to smaller more focused classes and cleaner interfaces.
4. Units tests act as documentation: Testing functions are understandable examples of how the production code should be used
5. TDD ensures consistent testing off all resources throughout the development of a piece of software

10.2.1 Unit Tests

Unit tests as already mentioned are tests that determine if individual units of source code are fit for use. It is important that unit tests are written very simply in order to ensure correctness (since there is no tests to ensure that the unit tests are correct). The following is a simple example of a test function and the corresponding production code it is intended to test.

Unit Test:

```
1 void testAdd(){
2
3     int expectedAnswer = 5;
4     int answer = add(3 ,2);
5
6     TEST_ASSERT(expectedAnswer == answer); //Check to see if output is as expected, and make
7         record if it is not.
8 }
```

Production code (under test):

```
1 int add(int a, int b){
2     return a*b; //Obviously this will cause the test to fail
3 }
```

Obviously the above test will fail because the function `add()` has been implemented incorrectly. Using a Unit testing library such as CppTest we will receive the following output:

```
1 FailTestSuite: 0/0, 0% correct in 0.000002 seconds
2   Test:      testAdd
3   Suite:     ExampleSuite
4   File:      mytest.cpp
5   Line:      9
6   Message:   "expectedAnswer == answer"
```

10.2.2 TDD Implementation in the FCST

The unit testing structure that is implemented in the FCST is built using a library called CppTest. CppTest is a portable, powerful and simple, unit testing framework for handling automated tests in C++. The focus lies on usability and extendability.

Several output formats, including simple text output, compiler-like output and HTML, can be produced. The tests suit is launched from the system builder class's `run_tests()` function, see 10.2. Firstly unit tests are run (which will tests individual components of various classes), then system level tests (similar to the tests already implemented by Michael Moore).

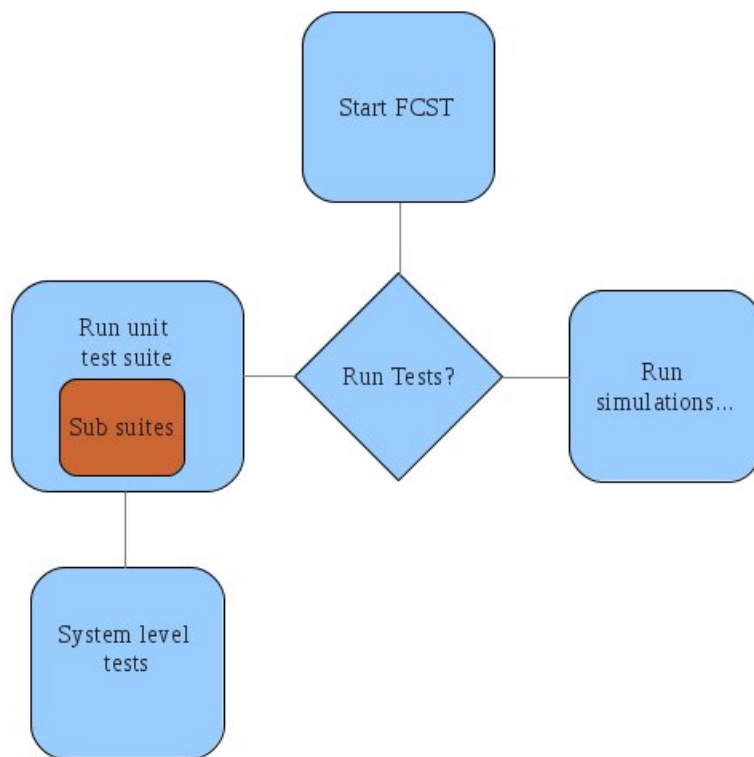


Figure 10.2

The operation is as follows:

The “Run tests” parameter is set in the main parameter file.

```
1 set Run tests = true
```

The run test function in SimulatorBuilder is called, which in turn calls the FCST testing suite.

```
1 void SimulatorBuilder<dim>::run_test ()
2 {
3 deallog << "=====Running Unit Tests===== " << std::endl;
4
5 FcstTestSuite::run_tests ();
6
7 deallog << "=====System Tests Complete===== " << std::endl;
```

The FCST test suite runs all of the unit testing suites that it is composed of (currently only the FCST units testing suite)

```
1 bool FcstTestSuite::run_tests ()
2 {
3 Test::Suite ts;
4
5 //add sub tests suites
6 ts.add(std::auto_ptr<Test::Suite>(new FcstsUnitsTestSuite));
7 ts.add(std::auto_ptr<Test::Suite>(new IonomerAgglomerate3Test));
8
9 Test::TextOutput output (Test::TextOutput::Verbose);
10 return ts.run(output);
11
12 }
```

Below is an example of an individual “sub” testing suite. Each individual unit test is added to the test suite in the constructor and will be called individually when the .run() function is called.

```
1 #ifndef FCST_UNITS_TESTSUIE
2 #define FCST_UNITS_TESTSUIE
3
4 #include <cpptest.h>
5 #include "fcst_units.h"
6
7
8
9 class FcstsUnitsTestSuite: public Test::Suite
10 {
11 public:
12 FcstsUnitsTestSuite ()
13 {
14 //Add a number of tests that will be called during Test::Suite.run()
15 //Generic cases
16 TEST_ADD(FcstsUnitsTestSuite::perBigToSmallTest);
17 TEST_ADD(FcstsUnitsTestSuite::bigToSmallTest);
18 TEST_ADD(FcstsUnitsTestSuite::perSmallToBig);
19 TEST_ADD(FcstsUnitsTestSuite::smallToBig);
20
21 //specific Cases
22 TEST_ADD(FcstsUnitsTestSuite::btuToKwh);
23 TEST_ADD(FcstsUnitsTestSuite::kwhToBtu);
24 }
25 protected:
```

```

26     virtual void setup()    {} // setup resources... called before Test::Suite.run()
27     virtual void tear_down() {} // remove resources...called after Test::Suite.run()
28
29 private:
30     //Generic cases
31     void perBigToSmallTest();
32     void bigToSmallTest();
33     void perSmallToBig();
34     void smallToBig();
35
36     //Specific cases
37     void btuToKwh();
38     void kwhToBtu();
39 };
40
41 #endif

```

Below is an example of an individual unit test taken from the “FcstsUnitsTestSuite” test suite. It checks that the function convert correctly converts units of BTU to units of KJ.

```

1 void FcstsUnitsTestSuite::btuToKwh()
2 {
3     TEST_ASSERT(Units::convert(1,Units::BTU_to_KJ) == 1.054);
4
5 }

```

10.2.3 Implementing a new test suite

If you would like to add a unit test suite for a class that you are creating, follow these steps:

1. Create the class_test.h and class_test.cc files in the unit_test folders (use the existing .h and .cc files as templates)
2. Add an include statement to your new class_test.h file in FCST_TEST_SUITE.h (under code comment “List of sub suites”)
3. In FCST_TEST_SUITE.cc add your new test class in the run_tests() function

If you would like your test to be able to see private variables inside the class that it is testing you must add it as a friend to that class:

1. Go to the header of the class you are testing (class.h)
2. At the top of the file (outside namespace scope) make a reference to your test class (e.g. “class nameOfTestClass;”)
3. In the class’s declaration write the friend statement above the public section (e.g. “friend class ::nameOfTestClass;”)

10.2.4 Refactoring

Refactoring is a technique for restructuring existing code so to improve its readability and user understanding, without changing the behaviour of the code in anyway. When refactoring code a programmer looks for “Bad Programming Smells” and uses various methods to remove them. Code smells are not bugs, but weakness in code design that make code difficult to understand and can lead to bugs being introduced into the code.

Some examples of bad programming smells:

1. Duplicated code: identical or very similar code exists in more than one location.
2. Long method: a method, function, or procedure that has grown too large or complicated
3. Inappropriate intimacy: a class that has dependencies on implementation details of another class.
4. Too many parameters: a long list of parameters in a procedure or function make readability and code quality worse.
5. Complex conditionals
6. Temporary variables and fields
7. Use of primitives rather than objects
8. Classes and functions with multiple responsibilities

The following is an example of code that exhibits bad smells (see if you can spot them):

```
1 void sendMessage(Message dataToSend, string phoneNumber, string networkOperator){
2
3     string areaCode = "213";
4
5     if (networkOperator == "Rogers"){
6         string _phoneNumber = areaCode + "4" + phoneNumber;
7         MessageBuffer b;
8
9         for(int i=0; i < dataToSend.length(), i++)
10             b.pack(dataToSend[i]);
11
12         send(b, _phoneNumber)
13
14     }
15     else if(networkOperator == "Telus"){
16
17         string _phoneNumber = areaCode + "9" + phoneNumber;
18         MessageBuffer b;
19
20         for(int i=0; i < dataToSend.length(), i++)
21             b.pack(dataToSend[i]);
22
23         send(b, _phoneNumber)
24
25     }
26 }
```

Bad smells include local data (the area codes should not be stored locally but should be the responsibility of another class such as PhoneBook), and duplicate code inside either if statement. The following code represents the above code refactored. The refactoring patterns extract method has been used to replace the code from within the for loop, the pattern extract data has been used to remove the local variables areaCode as well as the if statement comparisons. The result is code that is shorter, more easily understood, and more easily reused.

```
1 void sendMessage(Message dataToSend, string phoneNumber, string networkOperator){
2
3     string fullPhoneNumber = PhoneBook::getAreaCode() + PhoneBook::getOperatorCode(
4         networkOperator) + phoneNumber;
5     MessageBuffer buffer = package(dataToSend);
6     send(buffer, _phoneNumber)
7 }
```

```
8 |
9 | MessageBuffer package(Message dataToSend){
10 |     MessageBuffer buffer
11 |
12 |     for(int i=0; i < dataToSend.length(), i++)
13 |         buffer.pack(dataToSend[i]);
14 |
15 |     return buffer;
16 | }
```

Also not the change of variable names. The new names do a better job at describing their purpose.

10.2.5 Unit Standards

This section will specify standards on what physical units are typically used in the FCST.

Chapter 11

Tracking and Ticketing System for FCST

The ESDLab group maintains a Tracking and Ticketing System for FCST at [the following site](#). In addition, TODO items can be added to the HTML documentation. See the HTML documentation for a complete list.

11.1 Tracking and Ticketing System Overview

11.2 Using the Ticketing System

Chapter 12

Daily FCST testing suite: CTest and CDash

12.1 Testing your code in your local directory

Before committing any changes to the repository, you should make sure that your working copy does not have any errors. You can test your working copy of FCST by typing the following in the command line in the FCST main folder:

```
1 $./run_tests
```

All test cases that have been programmed will be executed and the results will appear in two files in the main FCST folder. The first file created is the tests_summary.log, which will give a quick summary of the results of the tests, this will be opened automatically by the default text editor. The second file created is the full output from the simulation, this will be contained in tests_output.log. The summary from each test will be appended to the end of the output from each test.

At present there are two tests implemented, the app_cathode and app_pemfc test. The tests comprise of running the cases contained in the testing folder for each case (i.e. ./data/cathode/testing and ./data/pemfc/testing). Each test case has a data file containing expected results that will be compared to the results from the test. If they are not in agreement, an error message will be printed. To add another test to be run by ctest, first add the case to the list of tests. This list is contained in the ./test/CTestTestfile.cmake file. The command ADD_TEST is used:

```
1 ADD_TEST(app_cathode "tests/app_cathode_case.sh")
```

The first item is simply a name and can be anything that will describe the test being run. The second item is the location of the script that contains the test that is to be run. These scripts should always be put in the ./tests/ folder. The tests themselves are simply bash scripts that contain at least the call to the executable with the correct input data file. Additional capability is added that includes the printing of additional messages and comparison of expected and simulation results. To create a new bash script containing a test, please view the app_cathode.sh test case as an example (the case is given in the appendix):

The main features of a testing script should include:

- Runs the FCST executable using the correct data file.
- Compares the results to expected results.
- Determines whether the run was successful.
- Prints the results to the tests_summary.log file which will be copied to the main FCST folder.

Note that if you develop a new test case and feel it should be added to the nightly tests, then please speak to a CDASH administrator before committing the test script to the repository.

Chapter 13

Useful Programming Tips

13.1 Memory Leak Detection

Despite taking all precautions to avoid memory leaks, it is still a possibility. It is recommended that developers make use of the program Valgrind. It is a freely available, open-source software, and can be found in the software packaged with most Linux distributions. Valgrind checks memory operations of any program, without having to modify the program in any way. It will typically make the program run 20-50 times slower than normal. To run, simply call `valgrind --options` before your normal program call. E.g.

```
1 valgrind --leak-check=full --show-below-main=no --show-possibly-lost=no  
2 --show-reachable=no ./fuel_cell-2d.bin simulation.prm
```

will run FCST with a full memory leak check, while ignoring losses outside of the main program (system memory) and ignoring possible memory leak areas. This tool is particularly useful at pinpointing segmentation faults, etc.

See the Valgrind documentation for usage.

13.2 Working with pointers

As the complexity of FCST grows, it is easy to lose track of the dependencies between the applications and the classes that define the physics of the problem. FCST makes frequent use of pointers to pass information from one area of the code to another. Without careful tracking of pointers, it is possible to program memory leaks and memory faults into the program. It is recommended that two tools be used. First, the Boost Libraries implementation of smart pointers. Using these pointers ensures that memory will not be free'd if it is still in use. Furthermore, there is no need to explicitly `delete` data contained within a pointer, reducing the risk of a memory leak. The task to convert regular pointers to smart pointers is underway. For implementation, see the [Boost documentation](#)

13.3 Including files to the include files

In order to make sure that the include files in FCST are looked at first, please include files as follows: `#include "example.h"` instead of `#include <example.h>` for all FCST files.

13.4 Subversion tips

13.4.1 Setting the \$Id\$ Tag in Subversion

Subversion can be configured to set the tag when you check in a file.

This configuration has to be done client side. All developers must go through this procedure. Configure subversion to automatically add the \$Id: \$ tag do the following [6]

- Update your `/.subversion/config` by including the lines below. This configuration will automatically apply the `svn:keywords` property (which sets the *Id* tag) to all new files.

```
1 [miscellany]
2 enable-auto-props = yes
3
4 [auto-props]
5 *.h = svn:keywords=Id
6 *.cc = svn:keywords=Id
7 Makefile.in = svn:keywords=Id
```

- Set props on existing files. For existing files, you have to set the property manually. Go to the root of your source tree, and run this command:
- **NOTE:** For “*.h”, “*.cc” and “Makefile.in” files, the property has already been set in the repository. So, it isn’t required to do “propset” on these files. The following example code is for future use, for eg. setting property for new code files like Python script etc.

```
1 find . \( -name "*.h" -o -name "*.cc" \) -exec svn propset svn:keywords Id {} \;
```

- Go through each file and add the prototype *Id* tag. Do this at the comments header of each file as shown below

```
1 //-----
2 //
3 //   FCST: Fuel Cell Simulation Toolbox
4 //
5 //   Copyright (C) 2013 by Energy Systems Design Laboratory, University of Alberta
6 //
7 //   This software is distributed under the MIT License.
8 //   For more information, see the README file in /doc/LICENSE
9 //
10 //   - Class: electron_transport_equation.h
11 //   - Description:
12 //   - Developers: M. Secanell
13 //   - Id: $Id: $
14 //
15 //-----
```

13.5 Troubleshooting

13.5.1 Including new virtual functions in already existing classes

Please note that if you include a new virtual function to a class, you **must** perform a `make clean` before compiling the code again since all the classes that depend on the class you modified must be recompiled. Currently Make does not recognize this, therefore you must do it manually; otherwise you will get a **Segmentation Fault** error when running the program.

13.5.2 Corrupted double-linked list error

Sometimes, during code execution, following error is detected:

```
*** glibc detected *** /home/madhur/FCST/lib/fuelcell 2d.bin: corrupted double-linked list ***
```

This happens mostly due to compiler messing up the compiled files. When this happens, try cleaning the compiled files of FCST, using **make clean** and then re-compiling using **make**.

Bibliography

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- [2] M. Secanell, Computational Modeling and Optimization of Proton Exchange Membrane Fuel Cells, Ph.D. thesis, University of Victoria, November 2007.
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- [4] M. Secanell, R. Songprakorp, A. Suleman, N. Djilali. Multi-objective optimization of a polymer electrolyte fuel cell membrane electrode assembly. *Energy and Environmental Science*. 1:378-388, 2008.
- [5] Dobson P., Lei C., Navessin T., Secanell M, Characterization of the PEM fuel cell catalyst layer microstructure by nonlinear least-squares parameter estimation, *Journal of the Electrochemical Society*, 159:B514-B523, 2012.
- [6] <http://www.startupcto.com/server-tech/subversion/setting-the-id-tag>. Accessed on June 28, 2013.

13.6 Appendix

13.6.1 Example test script

```
1 #!/bin/bash
2
3 #####
4 # This file will run the app_cathode test that is contained in the data/cathode/testing
5 # folder. The script is run by ctest, keep in mind that the results that would normally
6 # be printed to screen will be suppressed by ctest and printed to its own file.
7
8 # The script will (by line number):
9 # (1) first navigate to the folder where the test is
10 # (2) will run the code with the correct data files.
11 # (3) The result from the simulation is queried to see if it ran without error by
12 # checking ${PIPESTATUS[0]}. A zero means the test ran without error.
13 # (4) If a non-zero result is returned by the simulation, the code will print out a
14 # message saying that there was an error. As this will also be suppressed by the
15 # code, the message is also printed to the tests_summary.log file. The first line
16 # containing a 'tee' command will create the file, subsequent calls will append
17 # their output to the end of the file, so as not to overwrite it.
18 # (5) Before exiting, the test_summary.log file is copied to the fctst main folder
19 # where it will be opened by the run_tests script.
20 # (6) If the simulation ran correctly, then the results from the simulation are
21 # compared to expected results. Both sets of results are stored in a texts files,
22 # appended with .dat. The test_comparison script is a python file that will read in
23 # the two files and compare them. If they are not within a reasonable agreement the
24 # python script will return a non-zero (7) and an error is printed. If they are in
25 # reasonable agreement, a zero is returned indicated that all is well and a message
26 # is printed. Again the message is captured by ctest, so it is also appended to the
27 # tests_summary.log file.
28 #####
29 (1) cd ../data/cathode/testing
30 (2) ../../lib/fuel_cell-2d.bin main_app_cathode_test.prm
31 (3) if [ "${PIPESTATUS[0]}" != "0" ]; then
32 (4) echo 2>&1 | tee tests_summary.log
33     echo "Results summary from app_cathode test:" 2>&1 | tee --append tests_summary.log
34     echo 2>&1 | tee --append tests_summary.log
35     echo "-----" 2>&1 | tee --append tests_summary.log
36     echo "The simulation did not run correctly. " 2>&1 | tee tests_summary.log
37     echo Please review the tests_output.log file " 2>&1 | tee tests_summary.log
38     echo "-----" 2>&1 | tee --append tests_summary.log
39 (4) echo 2>&1 | tee --append tests_summary.log
40 (5) cp tests_summary.log ../../tests_summary.log
41     exit 2
42 else
43 (6) ../../test/test_comparison.py dakota_tabular.dat test_results.dat
44     if [ "${PIPESTATUS[0]}" != "0" ]; then
45         echo 2>&1 | tee tests_summary.log
46         echo "Results summary from app_cathode test:" 2>&1 | tee --append tests_summary.log
47         echo 2>&1 | tee --append tests_summary.log
48         echo "-----" 2>&1 | tee --append tests_summary.log
49         echo "Results from the test do not match " 2>&1 | tee --append tests_summary.log
50         echo "expected results" 2>&1 | tee --append tests_summary.log
51         echo "Please check results in dakota_tabular.dat " 2>&1 | tee --append tests_summary.log
52         echo "against that of test_results.dat" 2>&1 | tee --append tests_summary.log
53         echo "-----" 2>&1 | tee --append tests_summary.log
54         echo 2>&1 | tee --append tests_summary.log
55         cp tests_summary.log ../../tests_summary.log
56 (7) exit 2
57     else
58         echo 2>&1 | tee tests_summary.log
59         echo "Results summary from app_cathode test:" 2>&1 | tee --append tests_summary.log
60         echo 2>&1 | tee --append tests_summary.log
```



```
61     echo "_____" 2>&1 | tee --append tests_summary.log
62     echo "Results from the test match expected results" 2>&1 | tee --append tests_summary.log
63     echo "_____" 2>&1 | tee --append tests_summary.log
64     echo 2>&1 | tee --append tests_summary.log
65     cp tests_summary.log ../../../../tests_summary.log
66     exit 0
67 fi
68 fi
```